Trusting the Cloud with Practical Interactive Proofs

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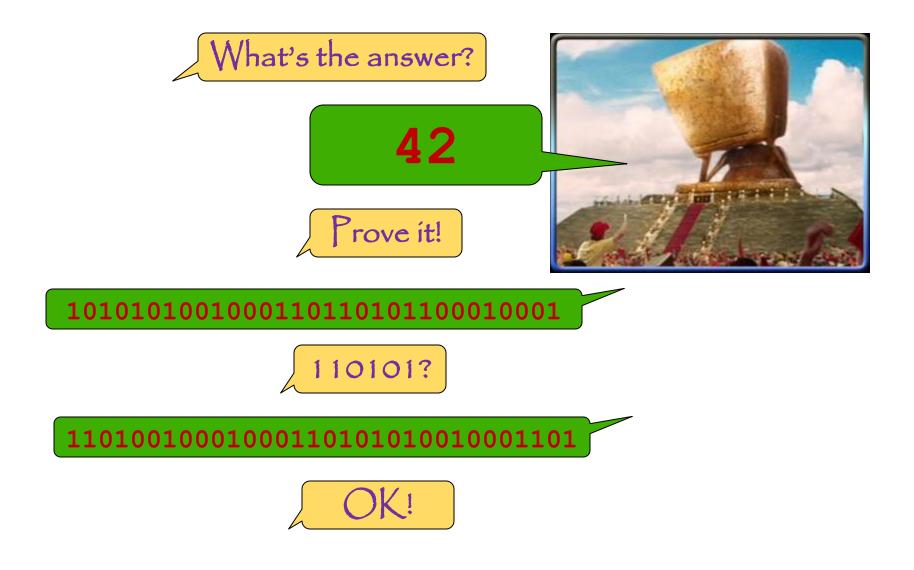
There are no guarantees in life

WE... MAKE NO REPRESENTATIONS ΔNY THE SERVICE OR WILL BE UNINTERRUPTED, THAT FREE OF HARMFUL COMPONENTS, TENT ... WILL BE SECURE OR NOT OTHERWISE LOST OR DAMAGED.

- From the terms of service of a certain cloud computing service...
- Can we obtain guarantees of correctness of the computation?
 - Without repeating the computation?
 - Without storing all the input?

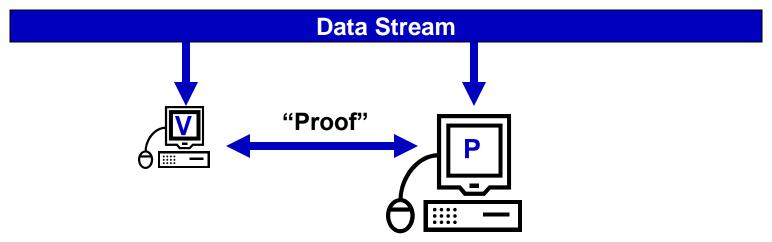


Interactive Proofs



(Streaming) Interactive Proofs

- Two party-model: outsource to a more powerful "prover"
 - Fundamental problem: how to be sure that the prover is honest?
- Prover provides "proof" of the correct answer
 - Ensure that "verifier" has very low probability of being fooled
 - Measure resources of the participants, rounds of interaction
 - Related to communication complexity Arthur-Merlin model, and Algebrization, with additional streaming constraints

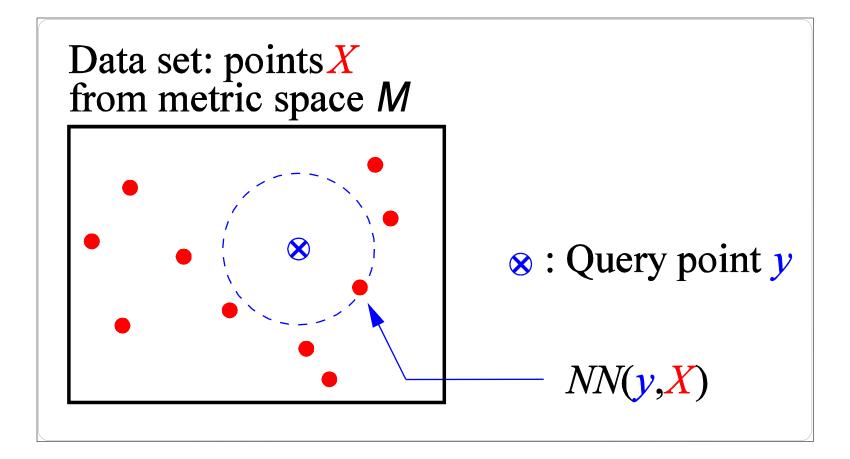


Starter Problem: Index



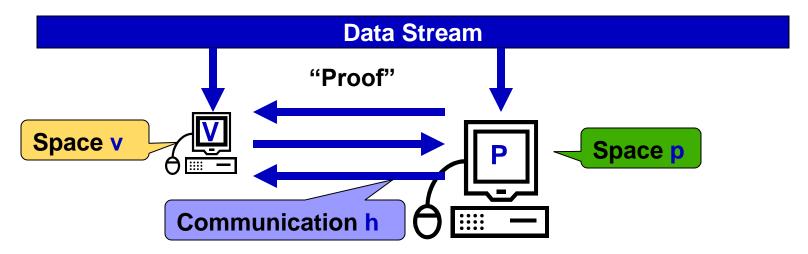
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- Fundamental (hard) problem in data streams
 - Input is a length m binary string x followed by index y
 - Desired output is x[y]
 - Requires $\Omega(m)$ space even allowing error probability
- Can we find a protocol to allow recovery of arbitrary bits
 - Without having the verifier store the entire sequence?

Real problem: Nearest neighbor

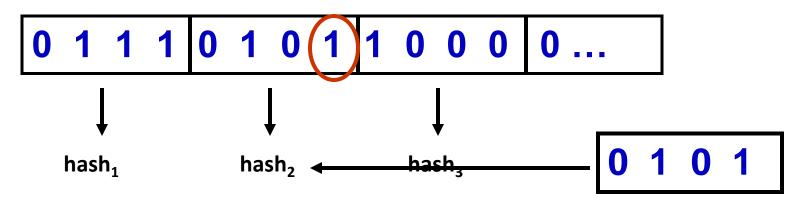


Parameters

- m data points (m very large)
 - Verifier V processes data using small space << m
 - Prover P processes data using space at least m
- V and P have a conversation to determine the answer
 - If P is honest, 0.99 probability that V accepts the answer
 - If P is dishonest, 0.99 probability that V rejects the answer
 - Measure the space used by V, P, communication used by both



Index: 1 Round Upper Bound



- Divide the bit string into blocks of H bits
- Verifier remembers a hash on each block
- After seeing index, Prover replays its block
- Verifier checks hash agrees, and outputs x[y]
- Cost: H bits of proof from the prover, V = m/H hashes
 - So HV = O(m log m), any point on tradeoff is possible

2 Round Index Protocol

Data indexed in Boolean hypercube {0,1}^b

Extended to hypercube **F**^b

Challenge line λ Random point $r \in \mathbf{F}^{b}$

- V picks r and evaluates lowdegree extension of input at r to get q
- 2. V sends λ to P
- 3. P sends polynomial p' which is input restricted to λ
- V checks that p'(r) = q, and outputs p'(y)

Query point y

Streaming LDE Computation

- Given query point $r \in F^b$, evaluate extension of input at r
- Initialize: z = 0
- Update with impact of each data point y=(y₁, ... y_b) in turn.
 Structure of polynomial means update causes

$$z \leftarrow z + \prod_{i=1}^{b} ((1-y_i)(1-r_i) + y_ir_i)$$

- Lagrange polynomial, can be evaluated in small space
- Can be computed quickly, using appropriate precomputed look-up tables

Correctness and Cost

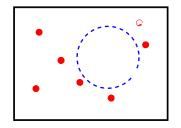
Correctness of the protocol

- If P is honest: V will always accept
- If P is dishonest: V only accepts if p'(r) = q
 This happens with probability b/|F|: can make |F| bigger
- Costs of the protocol
 - V's space: O(b log |F|) = O(log n log log n) bits
 - P and V exchange λ and p' as (b + 1) values in F, so communication cost is O(log n log log n) bits
 - Exponential improvement over one round
- Consequences: can do other computations via Index e.g. median
 - What about more complex functions?

Nearest Neighbour Search

Basic idea: convert NNS into an (enormous) index problem

- Work with input points in [n]^d
- Assume all distances are multiples of $\varepsilon = 1/n^d$
- Let B = {all distinct balls}; note |B| ≤ n^{2d}
 - Convert input points to **virtual set of balls** from **B**:
 - point $x \rightarrow$ all balls β such that $x \in \beta$
- V processes virtual stream σ through index protocol
- For query y ∈ X, P specifies point z ∈ X, claiming z = NN(y,X)
 - Show $ball(z,0) \in \sigma$ via Index Protocol
 - And ball(z, dist(y, z)- ε) $\notin \sigma$ via Index Protocol
- Protocol allows correct demonstration of nearest neighbour
- Drawback: blow-up of input size costs V a lot!



Practical Proof Protocol

Exploit structure of the metric space containing the points

- Let $\Phi(\beta, x)$ be the function that reports 1 iff x is in ball β
- Goal: query the vector $v[\beta] = \sum_{x \text{ in input}} \Phi(\beta, x)$
- $\Phi(\beta, x)$ has a simple circuit for common metrics (Hamming, L₁, L₂...)
- "Arithmetize" the formula to compute distances
- Transform formula Φ to polynomial Φ' via

 $G_1 \wedge G_2 \mapsto G'_1 G'_2 and \qquad G_1 \vee G_2 \mapsto 1 \text{-} (1 \text{-} G'_1)(1 \text{-} G'_2)$

• Low-degree extension of v: v'($B_1 \dots B_{2d \log n}$) = $\sum_x \Phi'(B_1 \dots B_{2d \log n}, x)$

- Can then apply Index protocol to v' v never materialized by P or V
- Final costs of the protocol:
 - Verifier can process each data point in time poly(d,log n)
 - Communication cost and verifier space both poly(d,log m,log n) bits

Concluding Remarks

- These protocols are truly practical
 - No, really, they are
- Also provide insight into the theory of Arthur-Merlin communication games



- Many open problems around this area
 - Extend to other data mining/machine learning problems
 - Prove lower bounds: some problems are hard
 - Evaluations on real data, optimization of implementations
 - Variant models: power of two provers...