

Reactive Power Support for Large-Scale Wind Generation

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Motivation (1)

- Utility-scale wind generation should be capable of:
 - Voltage regulation.
 - Dynamic reactive support.
- Provision of these services should be consistent with traditional generation.
- Wind-farms are composed of many distributed wind turbine generators (WTGs).
 - Behavior is vastly different to a single large generator.

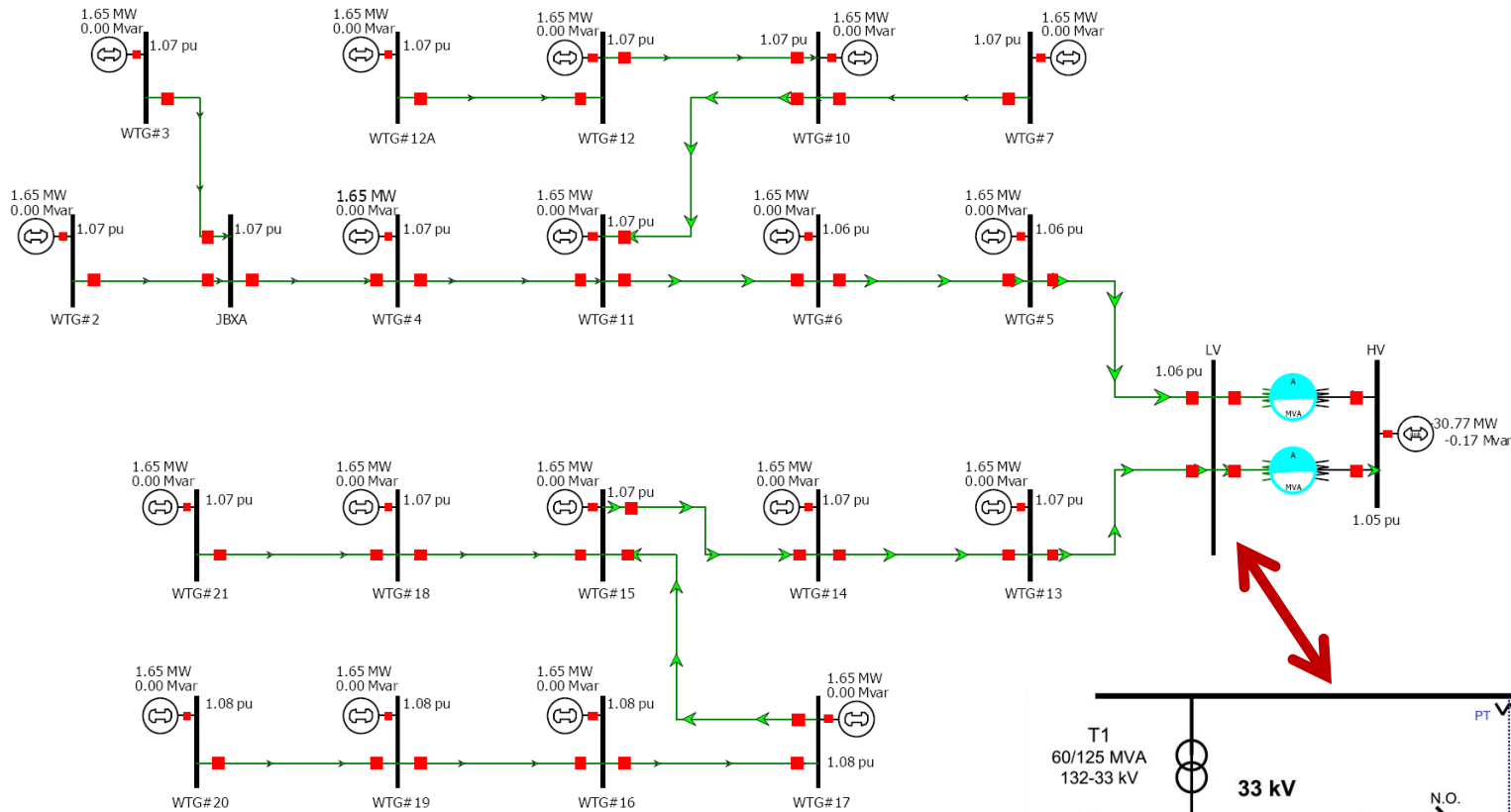
Motivation (2)

- A number of issues have been observed in practice:
 - Many wind-farms are located at lower (sub-transmission) voltage levels.
 - Actual reactive power available from wind-farms is less than predicted.
 - *Ad hoc* schemes are used to coordinate capacitor/reactor switching with Statcom/SVC controls.
 - Excessive switching, resulting in high circuit-breaker maintenance.
 - Reduced dynamic (fast acting) reactive reserve.

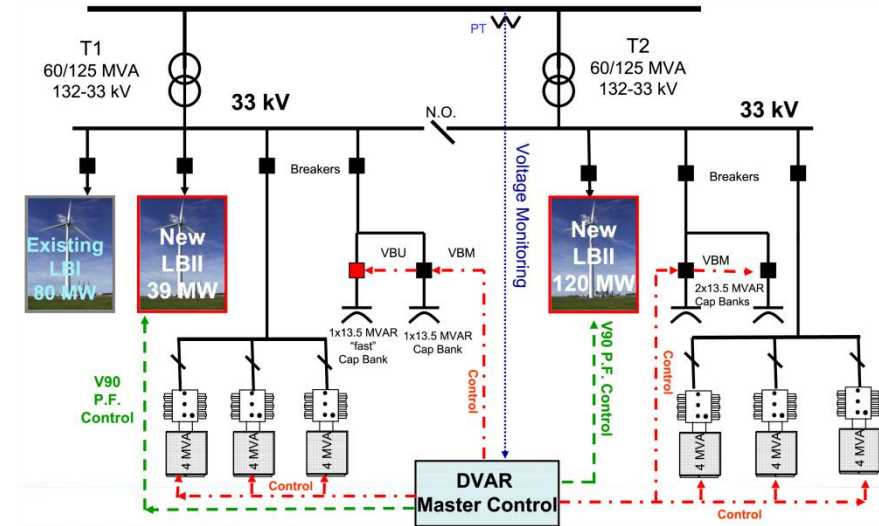
Outline

- Wind-farms on sub-transmission networks.
- Reactive power from the collector system.
- Coordination of wind-farm reactive sources.

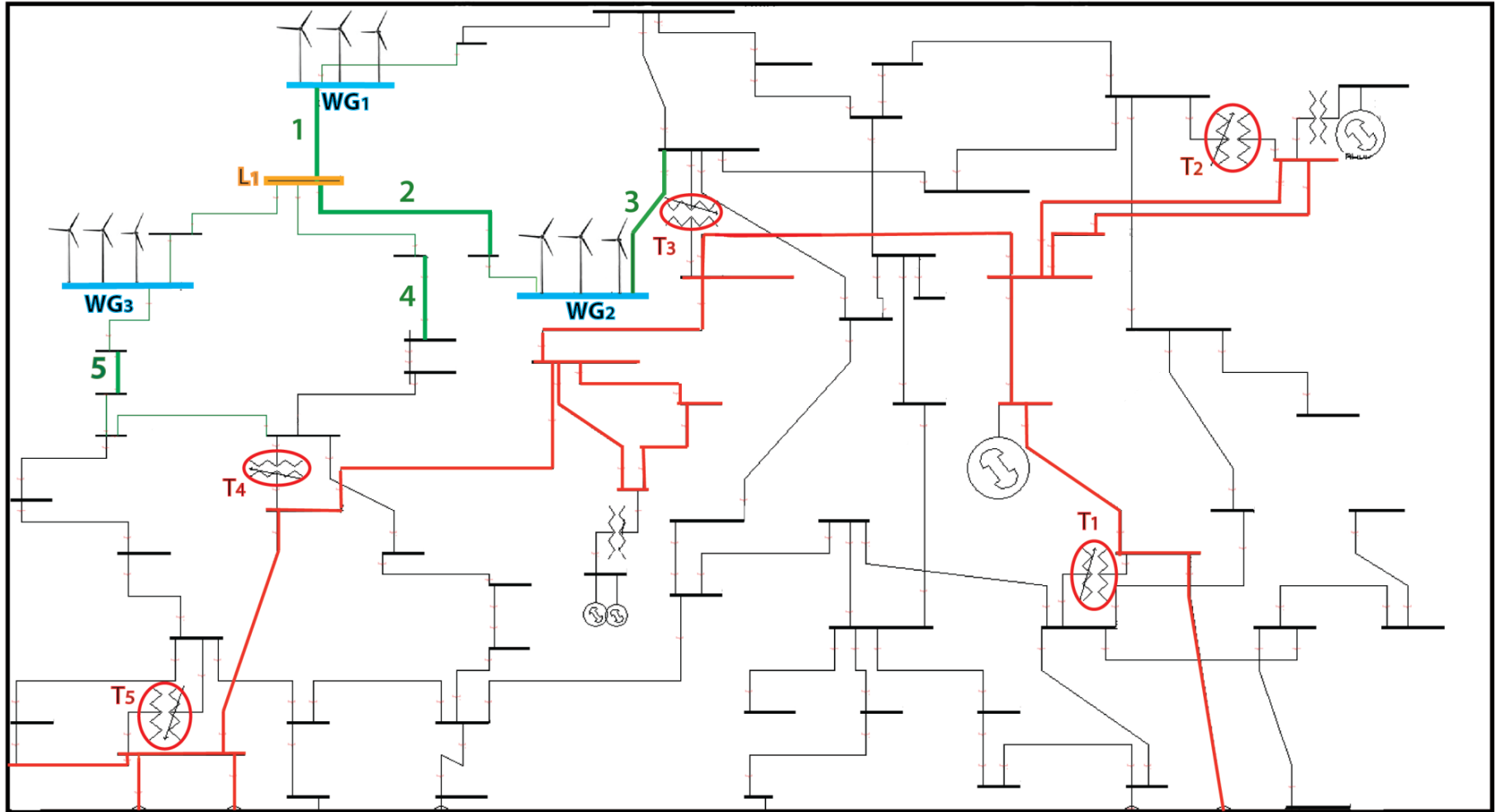
Wind-farm overview



Collector network



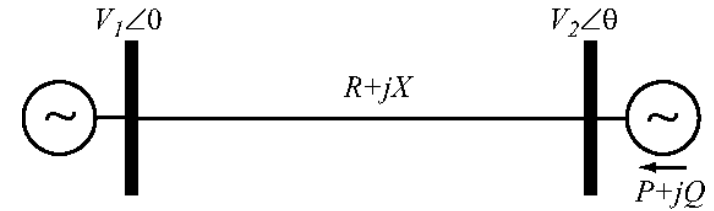
Wind-farms at sub-transmission



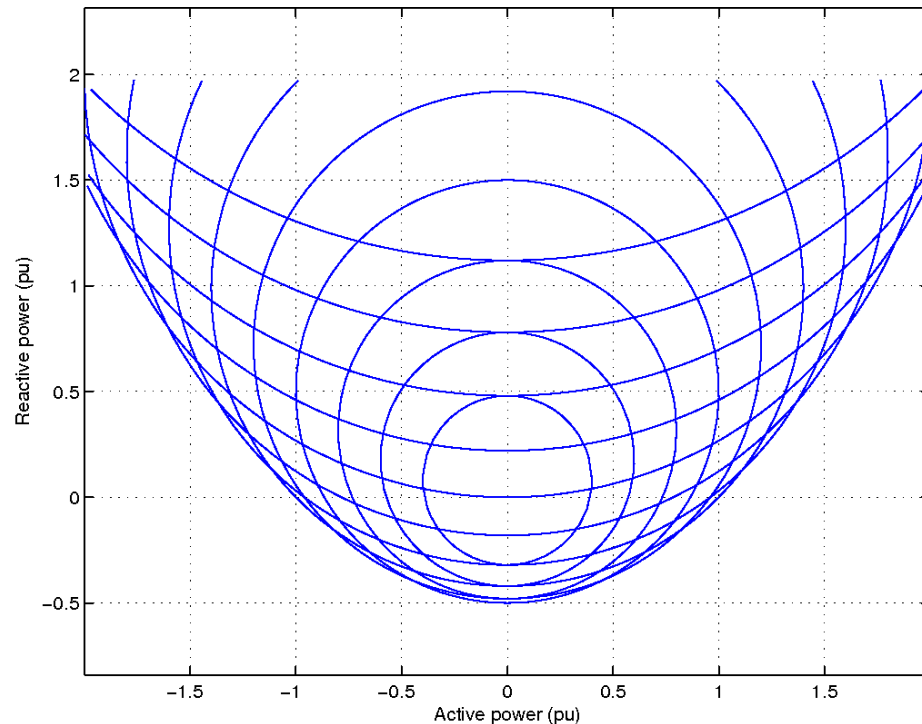
Effect of resistance

- Voltage contours for a two-node network:

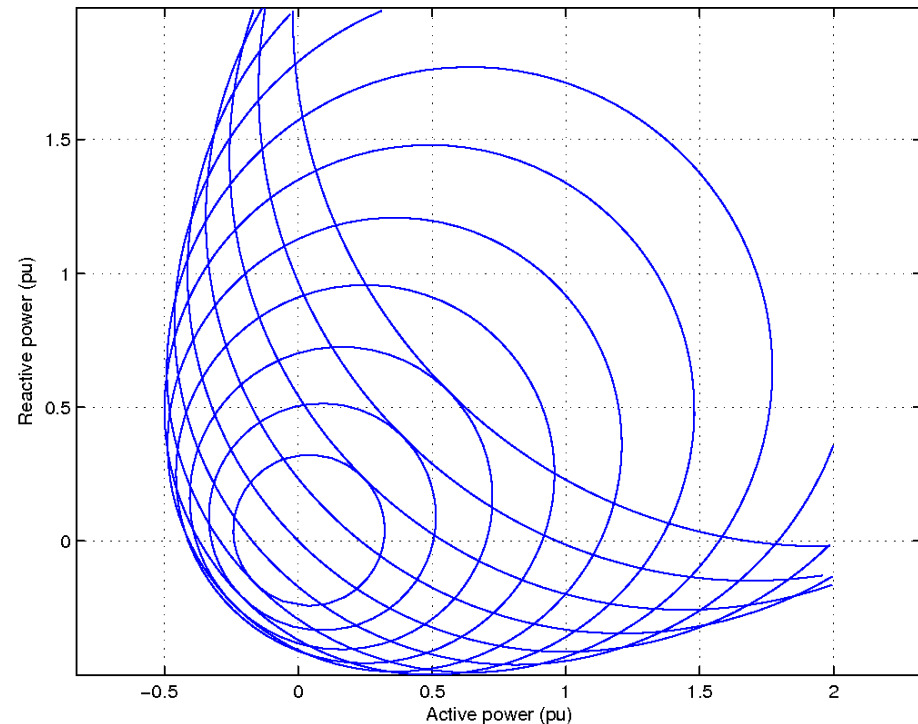
$$\left(\frac{V_2^2 R}{R^2 + X^2} - P \right)^2 + \left(\frac{V_2^2 X}{R^2 + X^2} - Q \right)^2 = \frac{V_1^2 V_2^2}{R^2 + X^2}$$

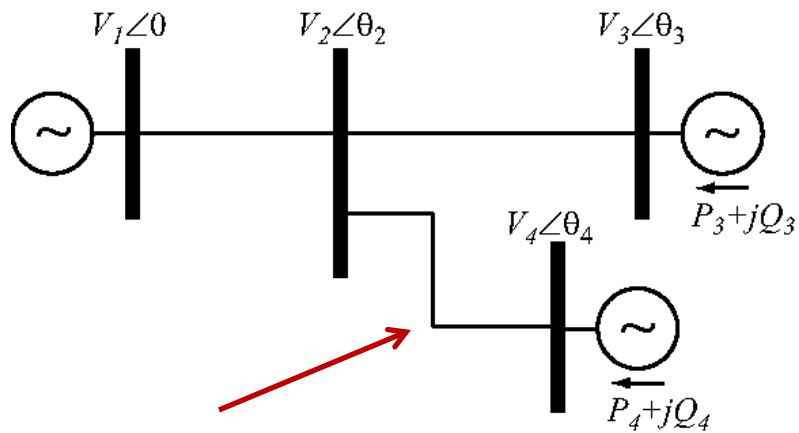


$R=0.0\text{pu}, X=0.5\text{pu}$



$R=0.5\text{pu}, X=0.5\text{pu}$

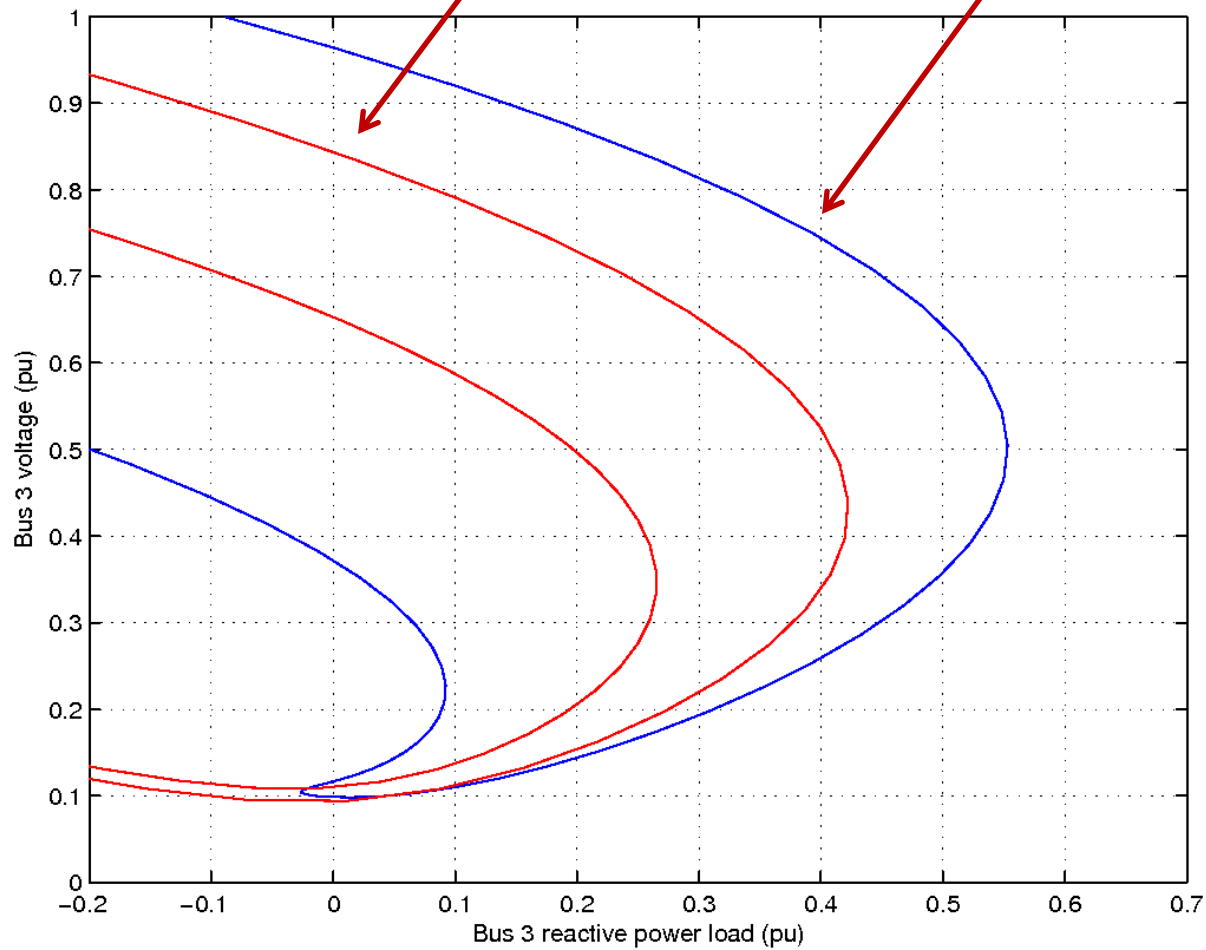




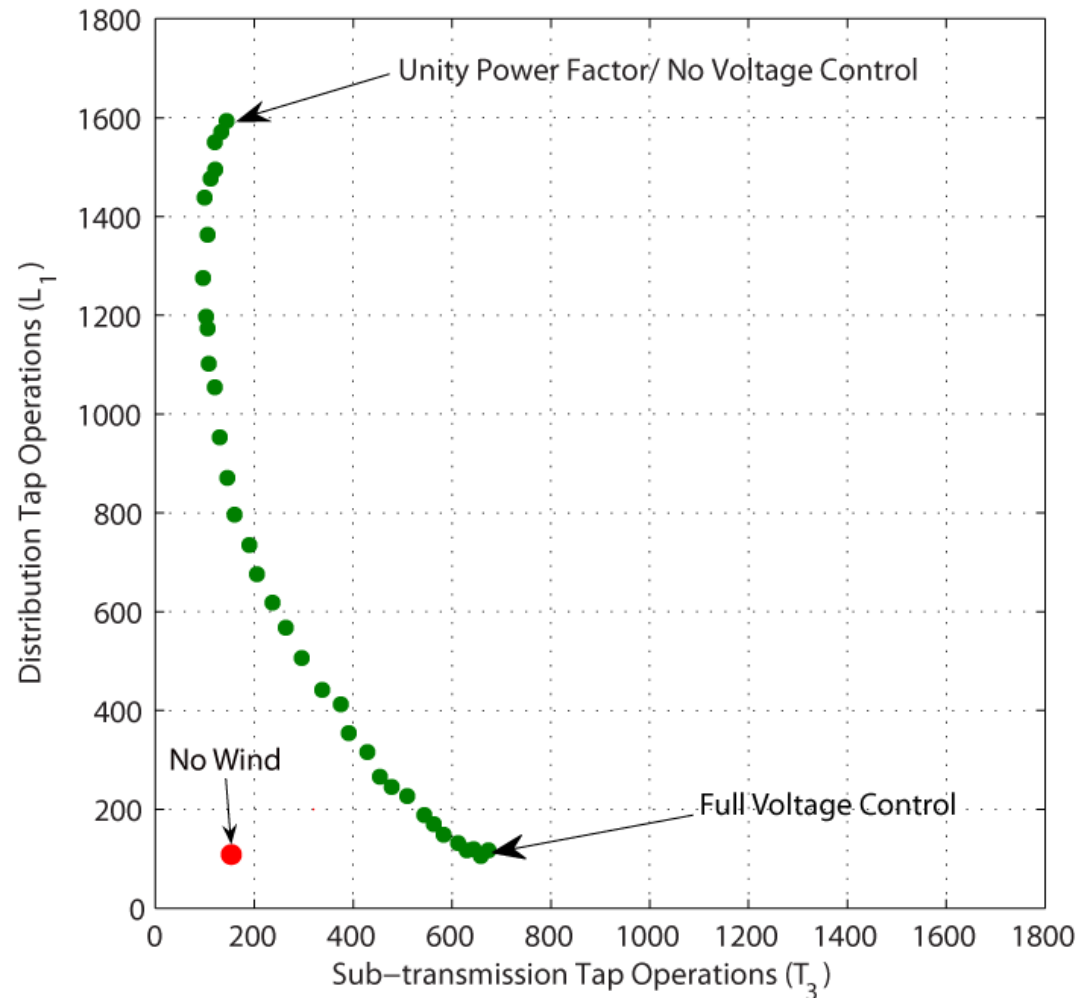
Resistive line

With resistance

No resistance



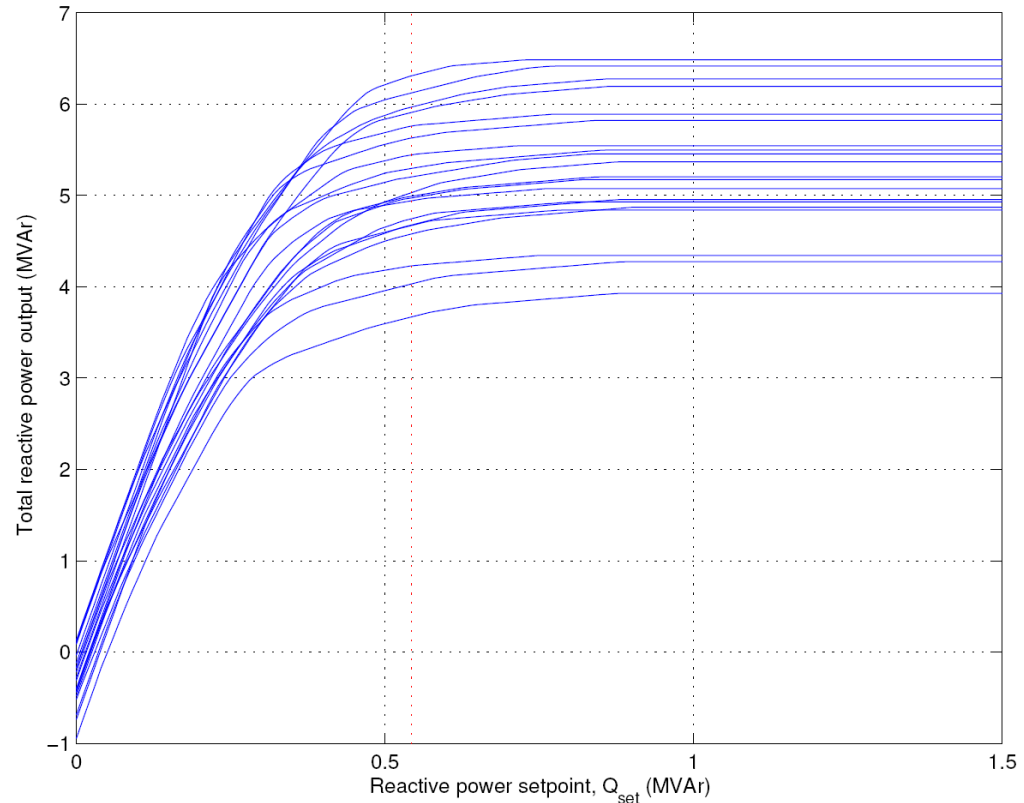
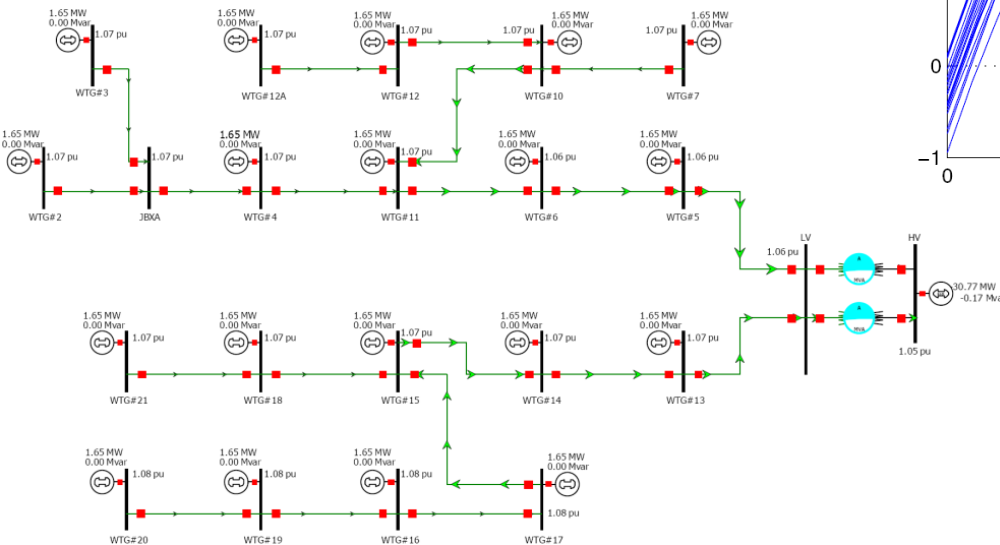
Wind-farm voltage control

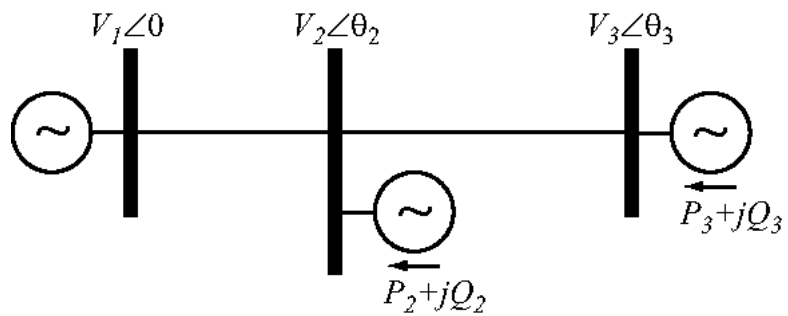


- Constant power factor/ limited voltage control:
 - Increased tap operations at distribution OLTCs.
 - Reduced tap operations at sub-transmission OLTCs.
- Full voltage control:
 - Reduced tap operations at distribution OLTCs.
 - Increased tap operations at sub-transmission OLTCs.

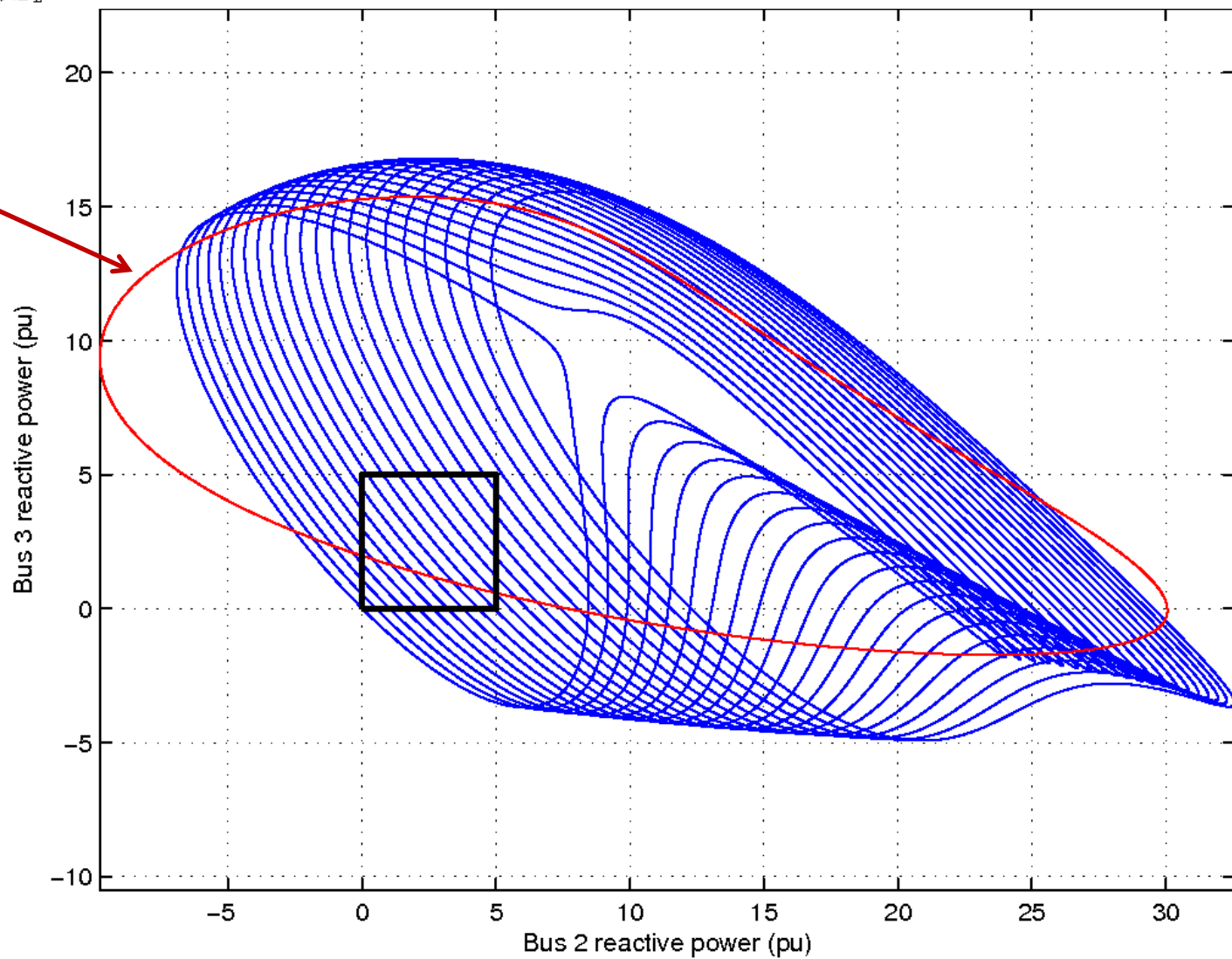
Reactive power availability

- Generator voltage limits restrict maximum available reactive power.

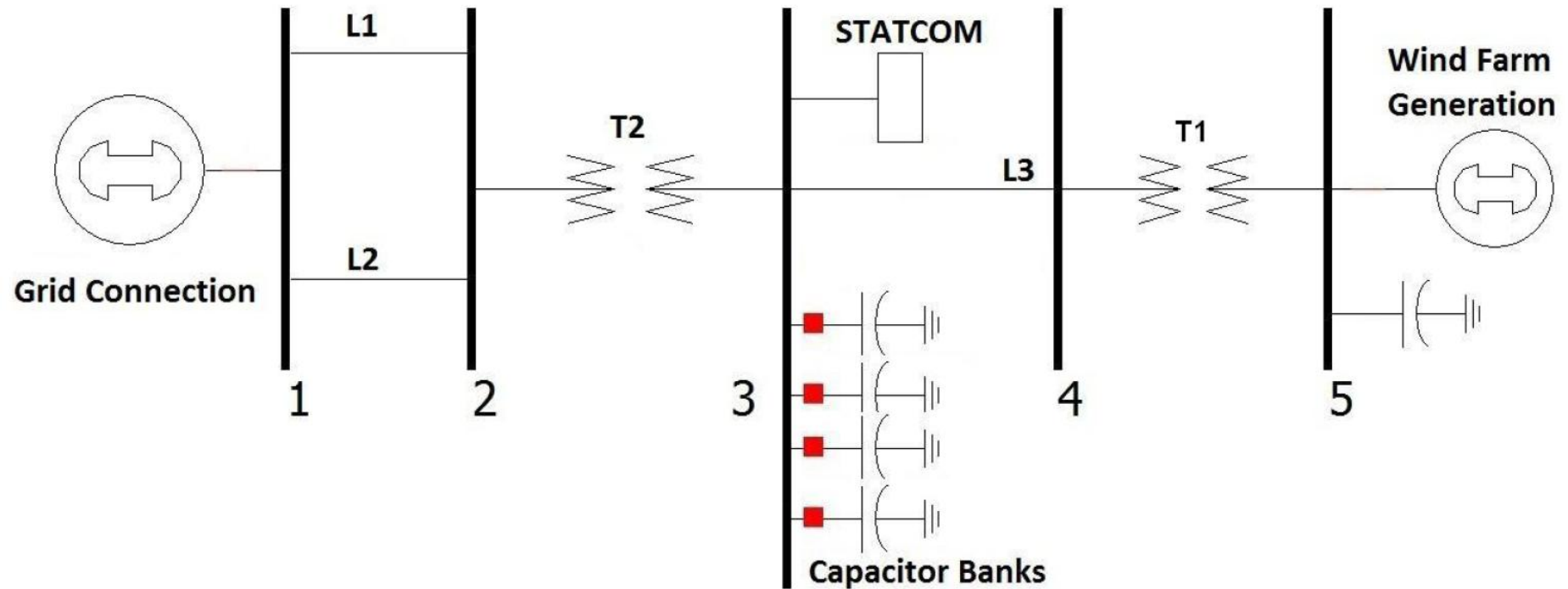




$V_3 = 1.1$ pu



Farm-level system optimization



$$\min \sum_0^T c_k(x, u)$$

such that

$$g_k(x_k, u_k) \leq 0 \quad \forall k$$

Information classes

- 1) **Exact Future Knowledge** - Exact knowledge of the future for the full time horizon.
- 2) **Stationary Stochastic Knowledge**- Stationary stochastic predictions about the future, no explicit forecasting.
- 3) **No Explicit Future Knowledge**- Both optimization- and rule-based methods.

Controllers with future knowledge

$$c_k(x_k, u_k) = \alpha N_{CS} + abs(\bar{S})$$

Number of Capacitor Switches
STATCOM Usage

↓
↙

Given Data

Objective

1) Exact future knowledge:
 Deterministic Dynamic
 Programming (DDP)

$P(t)$

$$\min \sum_0^T c_k(x, u)$$

such that

$$g_k(x_k, u_k) \leq 0 \quad \forall k$$

2) Stochastic knowledge:
 Stochastic Dynamic
 Programming (SDP)

$P(P_{k+1} | P_k)$

$$\min E_w \sum_0^\infty \gamma^k c(x, u)$$

such that

$$g(x, u) \leq 0 \quad \forall k.$$

Controllers *without* future knowledge

$$c_k(x_k, u_k) = \alpha N_{CS} + \text{abs}(\bar{S})$$

Given Data

Control Law

3a) No future knowledge:
Instantaneous optimization

None

$$u^*(x) = \underset{u \in U}{\operatorname{argmin}} c(x, u)$$

3b) No future knowledge:
Rule-based hysteresis

None

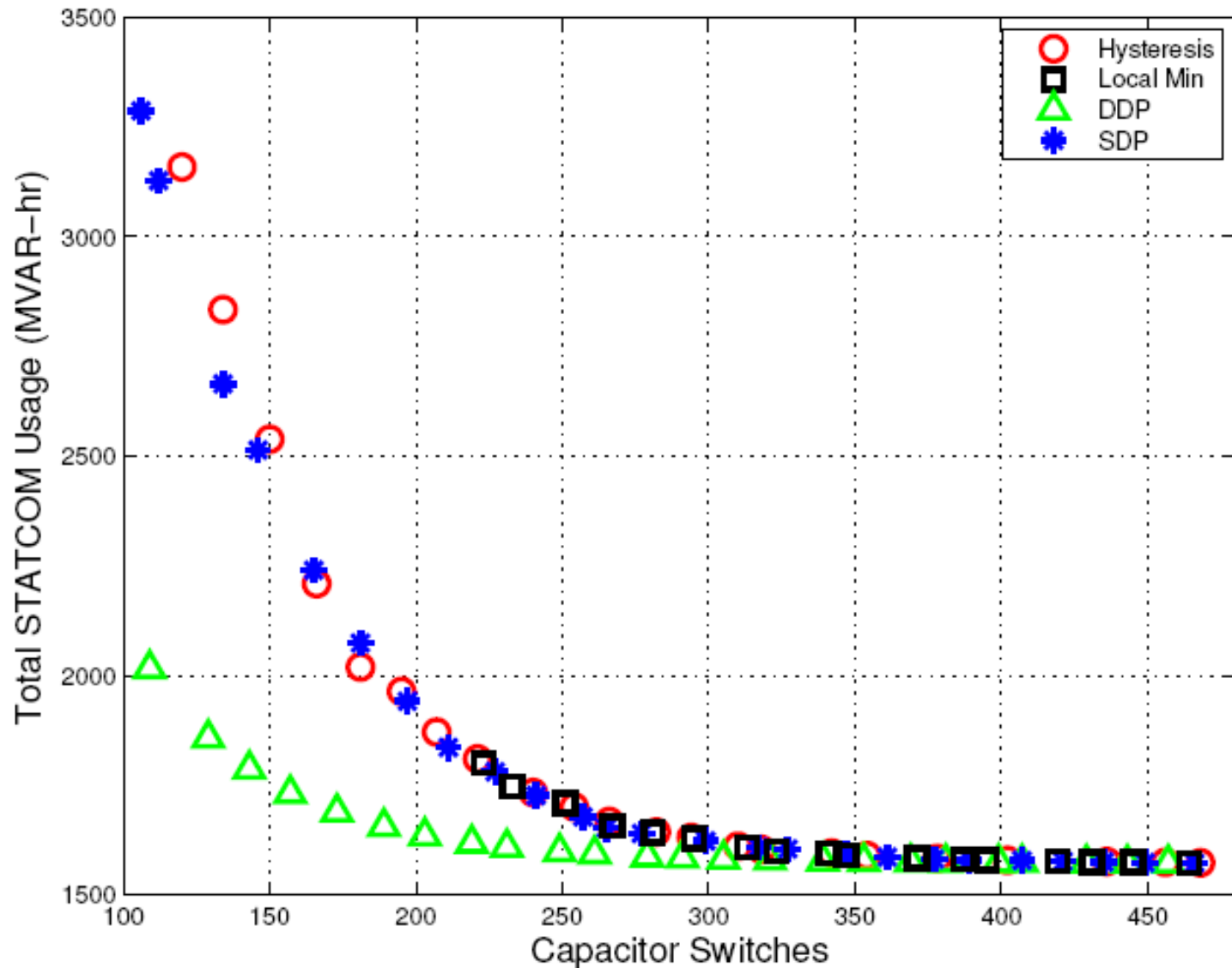
Threshold

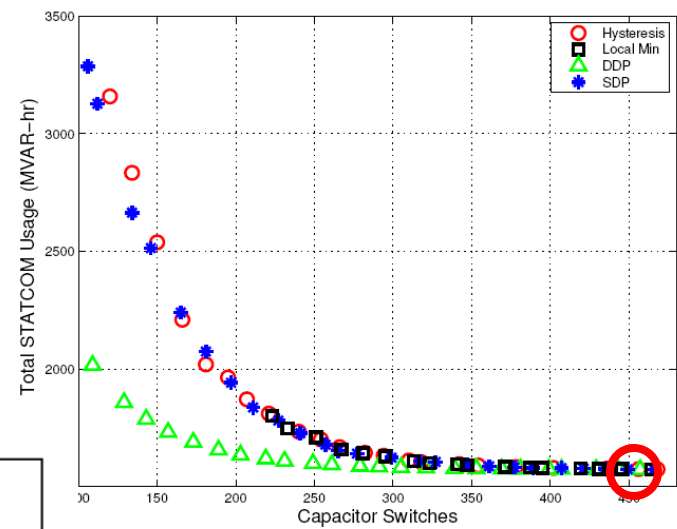
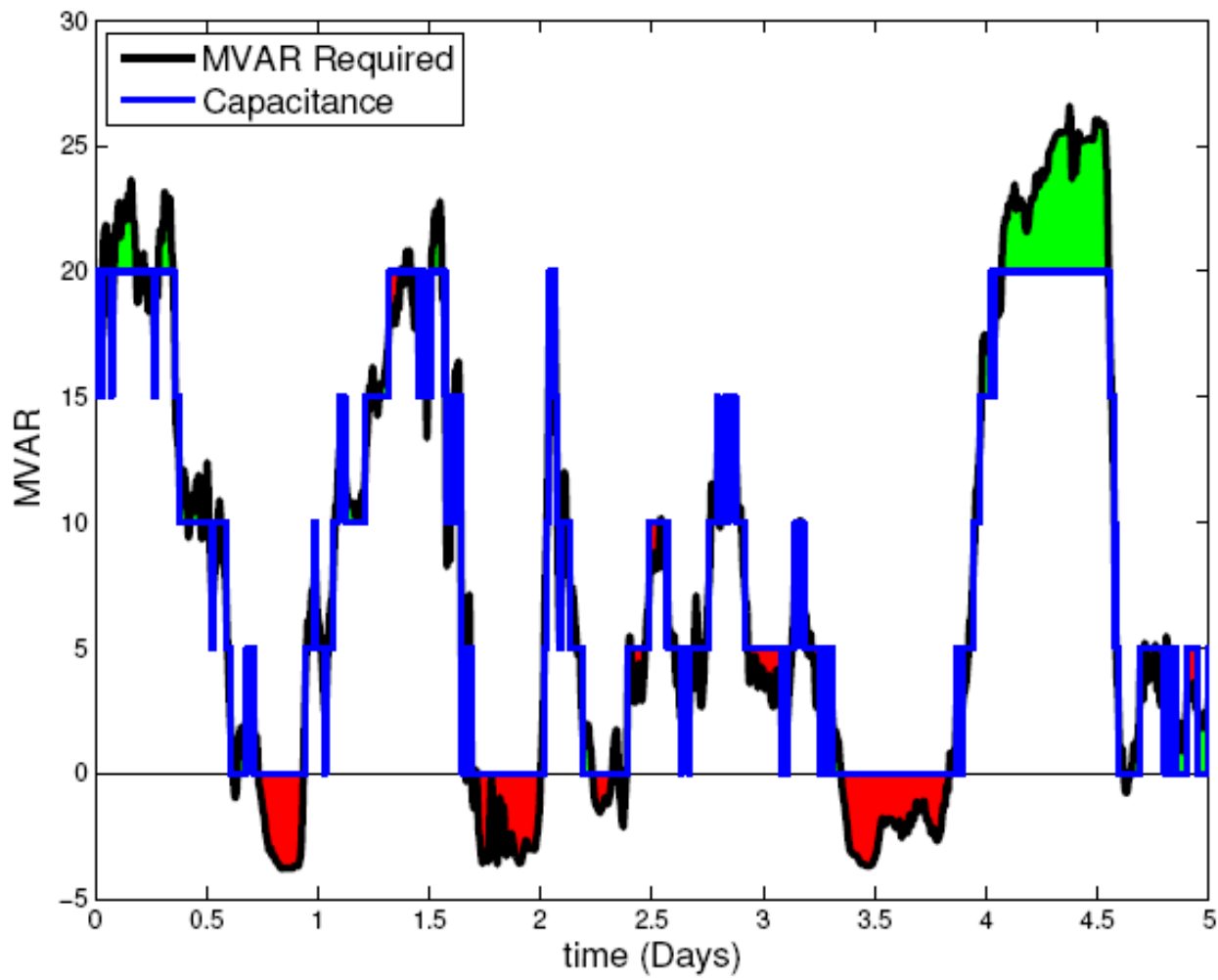
STATCOM Usage

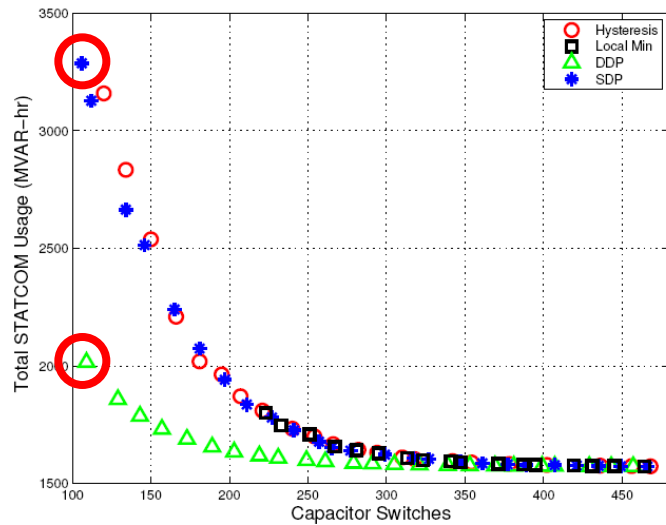
$$NC_{k+1} = \begin{cases} NC_k + 1 & \text{if } \bar{S} > \beta \\ NC_k - 1 & \text{if } \bar{S} < -\beta \\ NC_k & \text{otherwise.} \end{cases}$$

Number of Capacitors

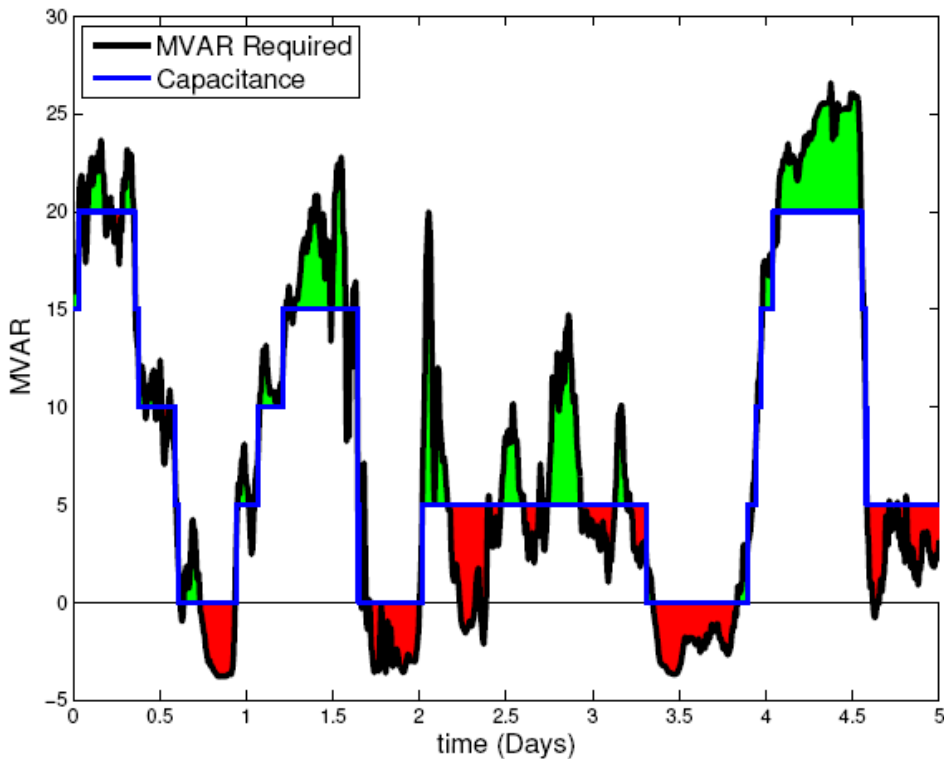
Capacitor switching versus Statcom



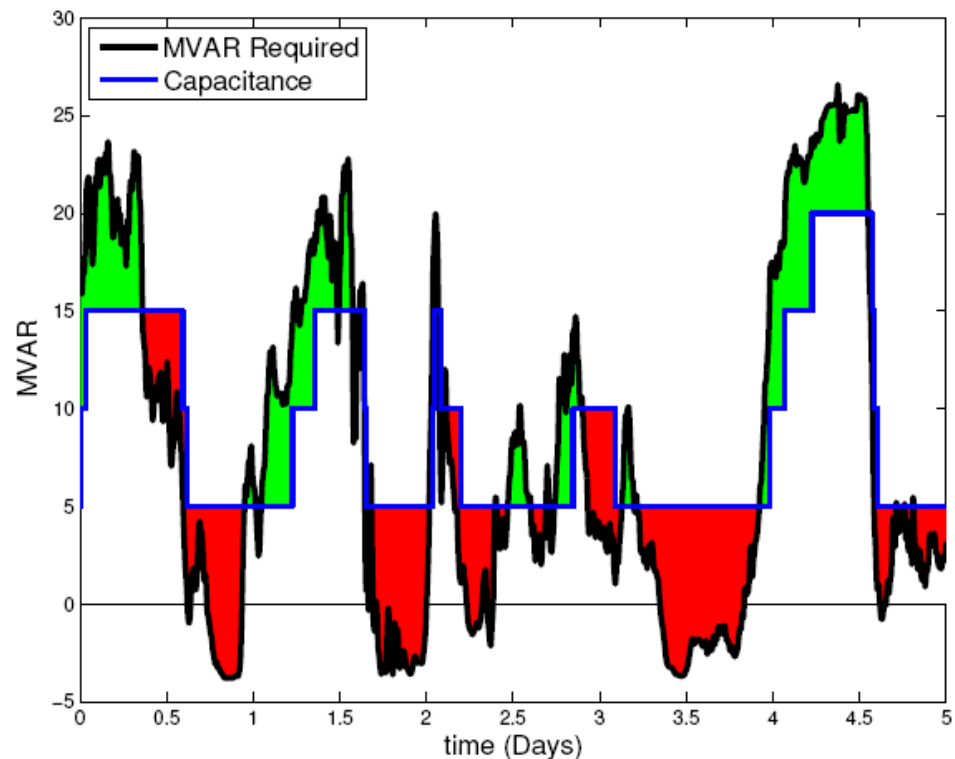




Exact future knowledge



Stochastic future knowledge



Conclusions

- Resistance can have an important, but non-intuitive, effect for wind-farms connected at the sub-transmission level.
- Total reactive power available from WTGs may be much less than expected.
- System-level control of substation equipment can improve performance, but future information is important.