Sampled-data Control and Signal Processing - Beyond the Shannon Paradigm

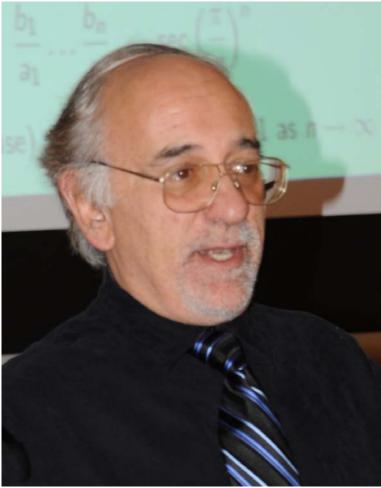
Workshop in honor of Eduardo Sontag on the occasion of his 60th birthday

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Thanks to



My schoolmate, dear friend, colleague, and even a teacher

One of the very rare pictures of Eduardo with a Tie: at my (YY) fest

Outline

- Current signal processing paradigm
 - Via Shannon
 - ⇒ Upper limit in high frequencies
- CAN BE SAVED via sampled-data control theory
- Some examples

Message of this talk

- We can do better in signal processing using sampled-data control theory
- ⇒ Optimal recovery of freq.
 components beyond the Nyquist freq. (=1/2 of sampling freq.)

Let's first listen to a demo



Red: Original (up to 22kHz) Blue: downsampled to 11k, and then processed 4 times upsampled via YY filter

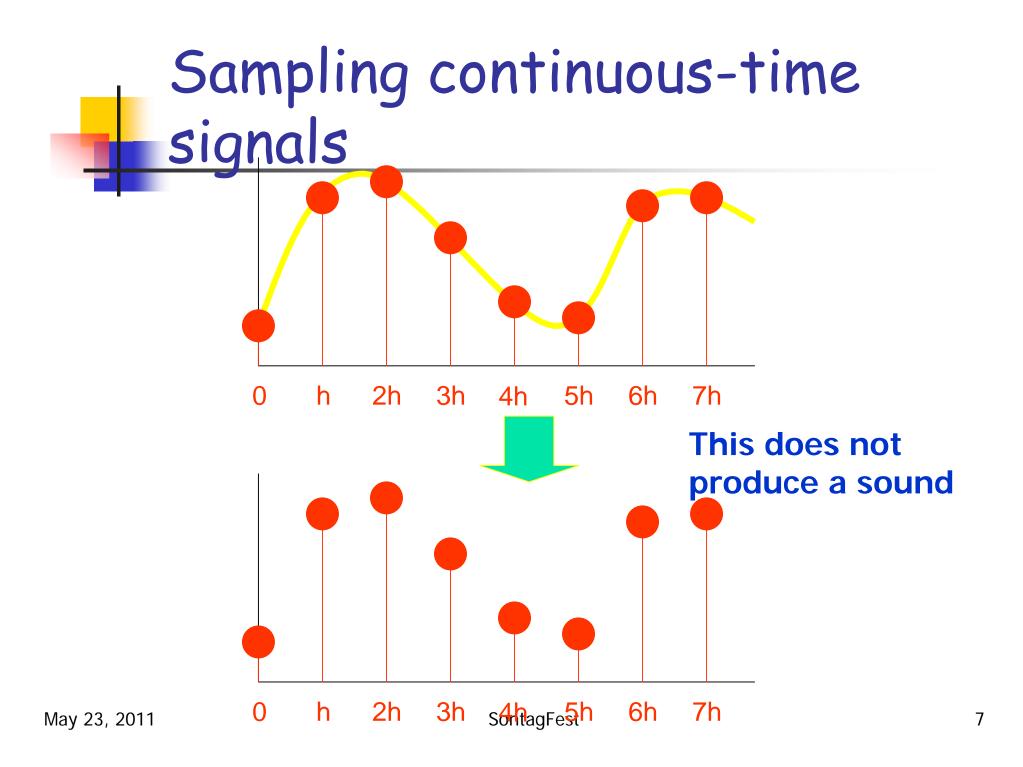
Did you hear the difference?

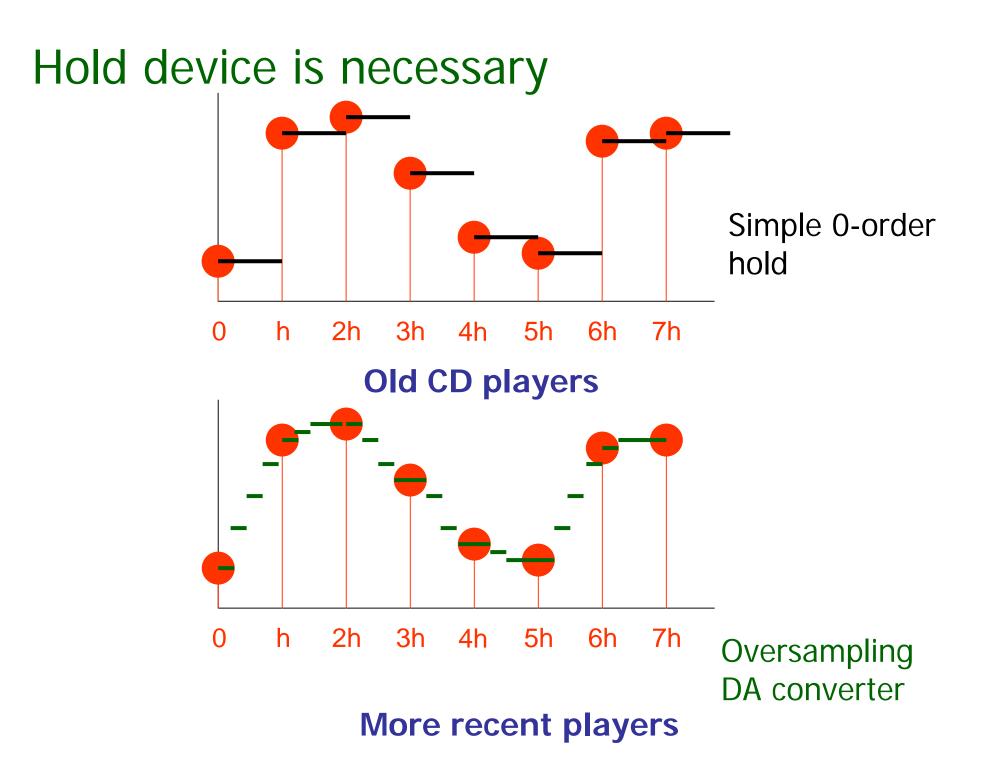
Part I: Current digital signal processing - Basics©

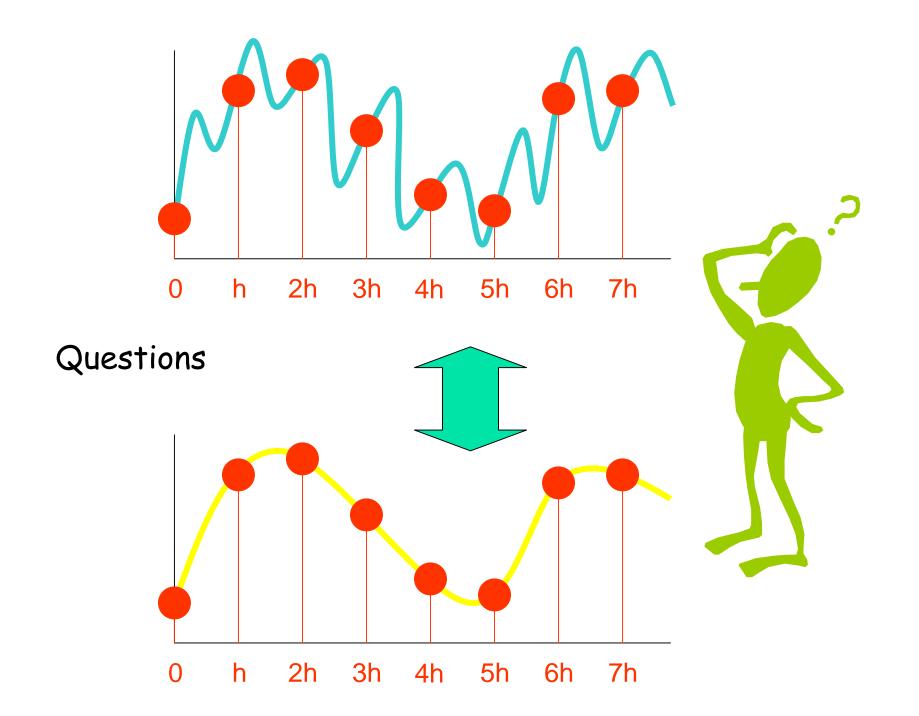
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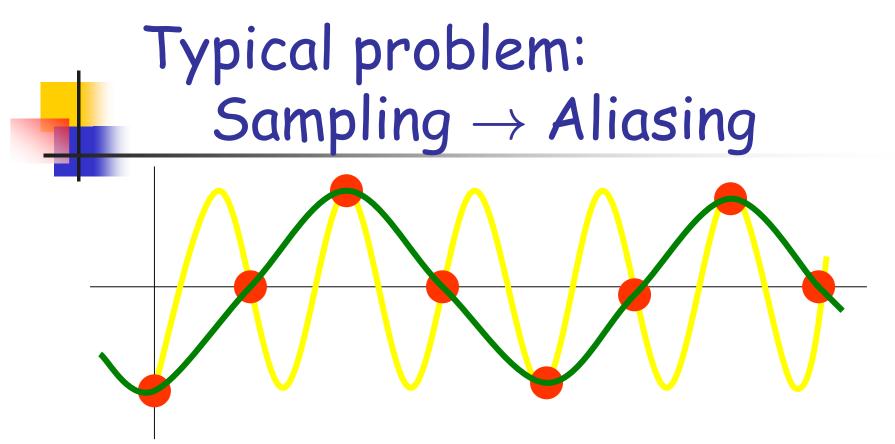
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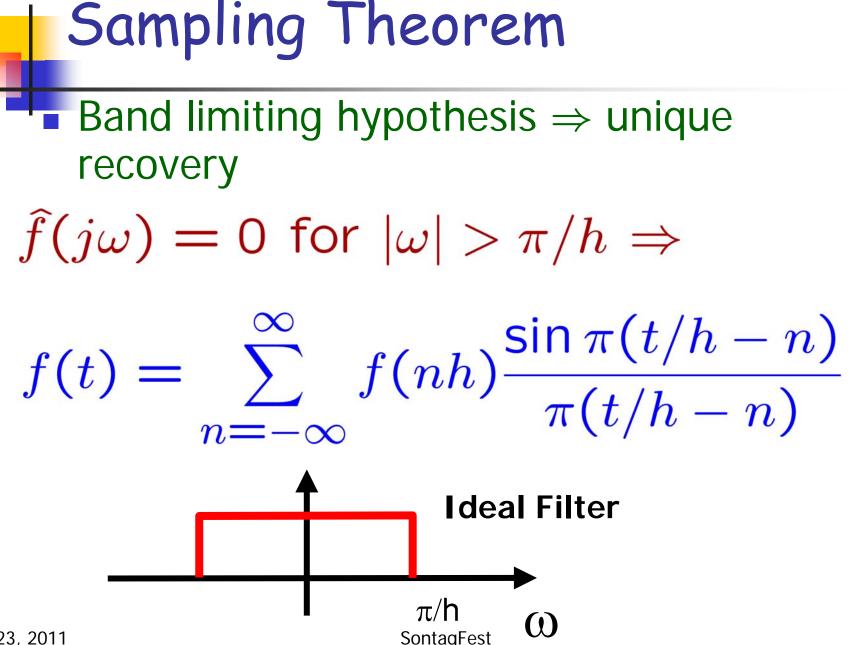




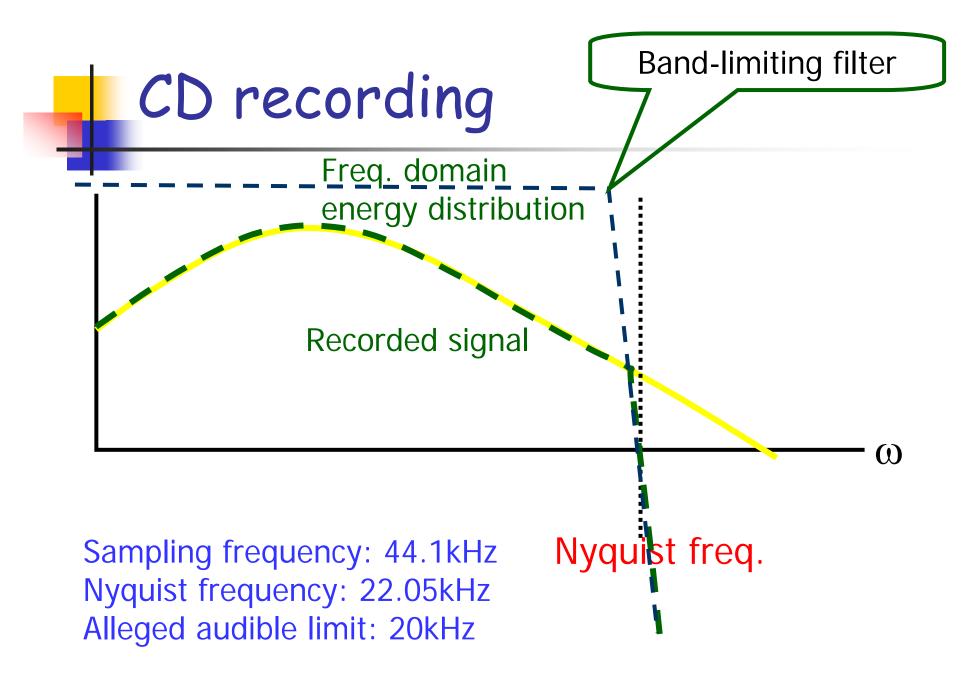


- Intersample information can be lost
- If no high-freq. components beyond the Nyquist frequency (=1/2 of sampling freq.) → unique restoration

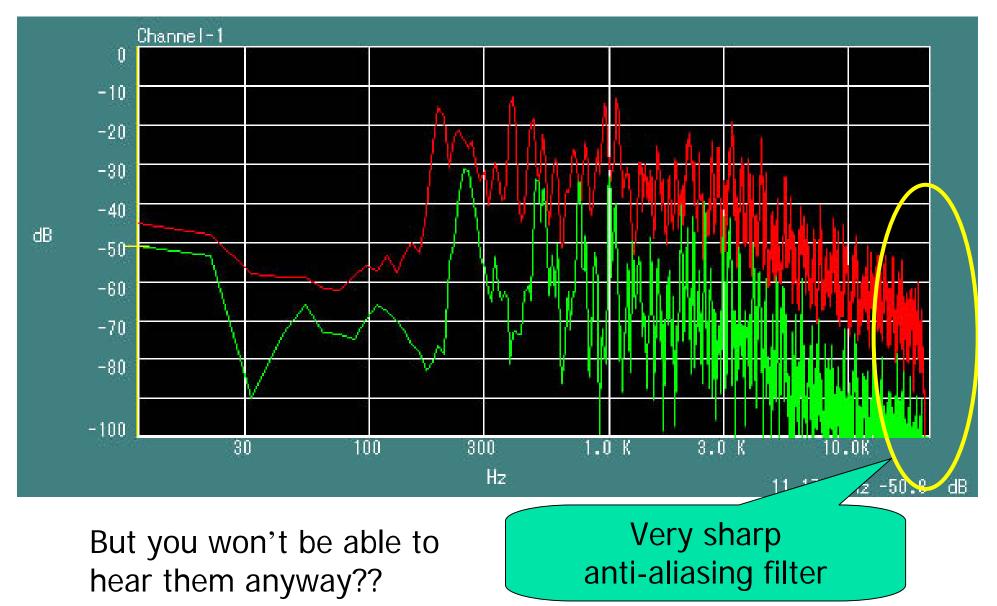
→ Whittaker-Shannon-Someya sampling theorem

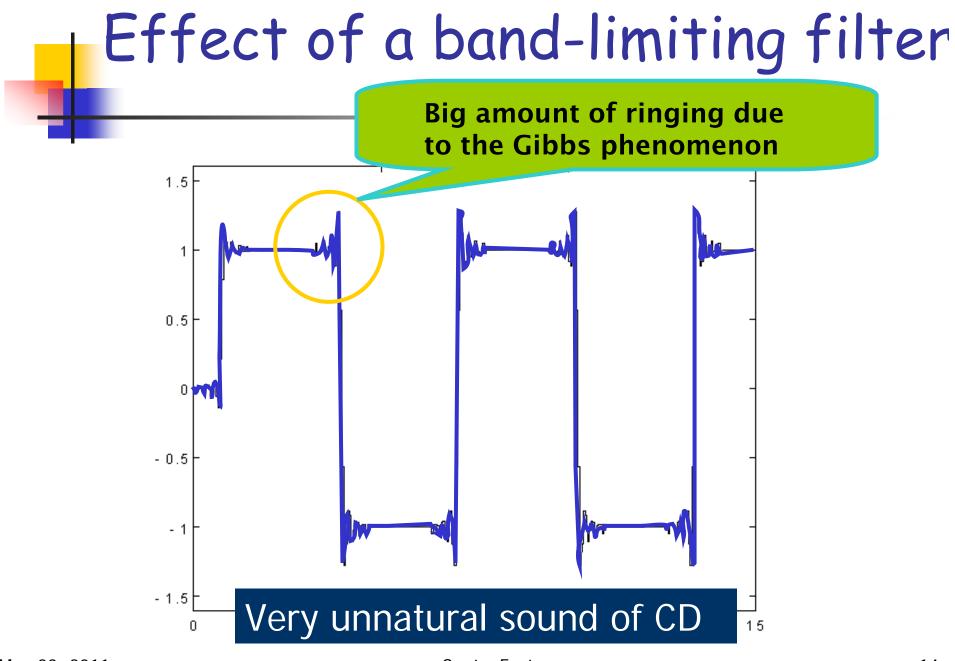


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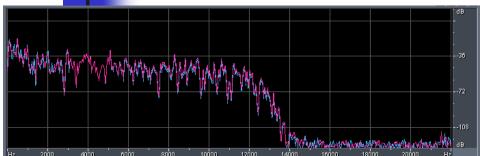


Digital Recording (CD): sharp anti-aliasing filter No signal components beyond 20kHz





Mosquito Noise-another Gibbs phoenomenon



Truncated freq. response

Autor and a state of the state

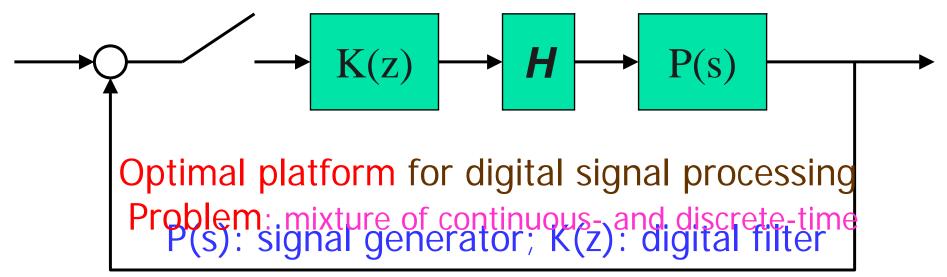


What can we do?

Part II: Review of Sampleddata Control Theory

Sampled-data Control Systems - What are they?

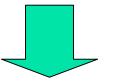
- Continuous-time plant
- Discrete-time controller
- sample/hold devices



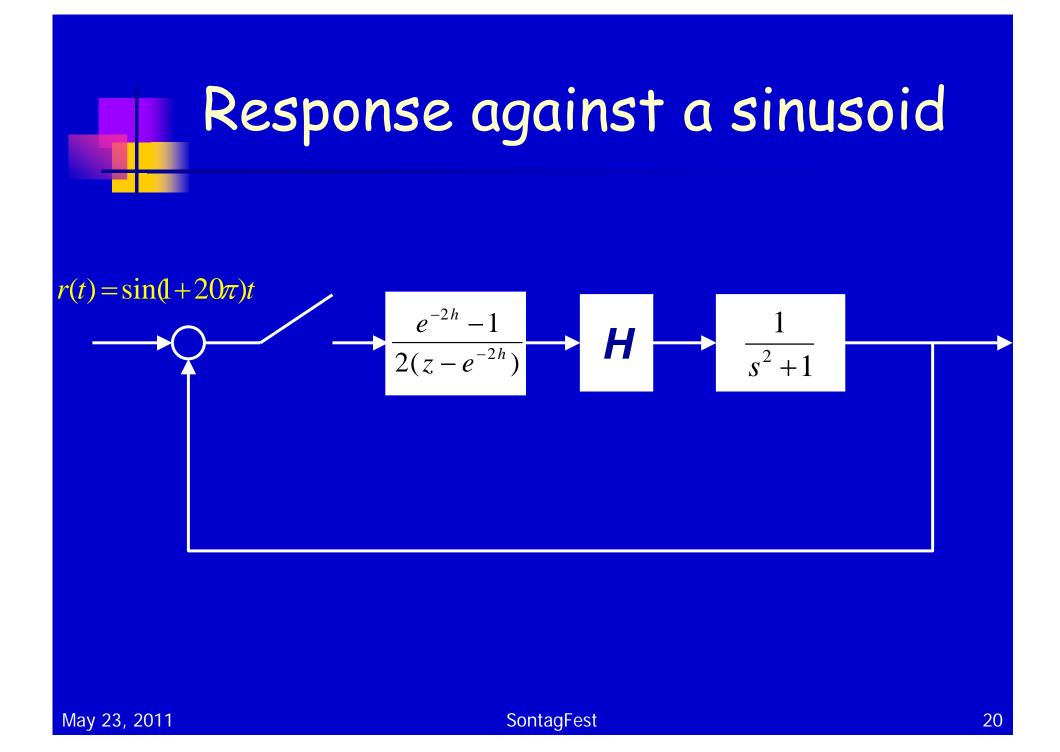


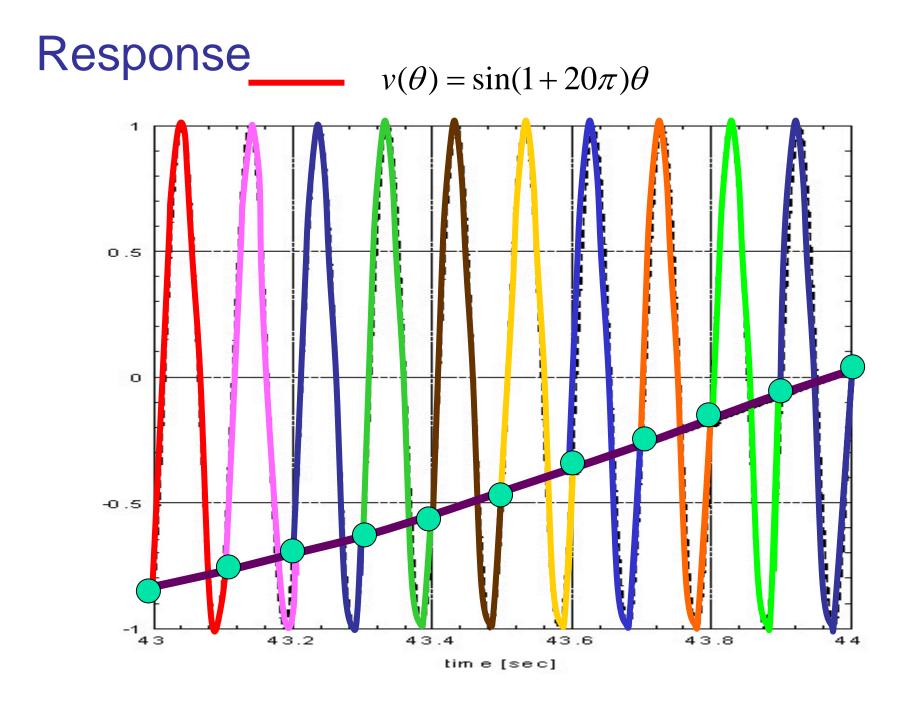
Difficulties

- Plant P(s) is continuous-time
- Controller K(z) is discrete-time
- The overall system is not timeinvariant



- No transfer function
- No steady-state response
- No frequency response



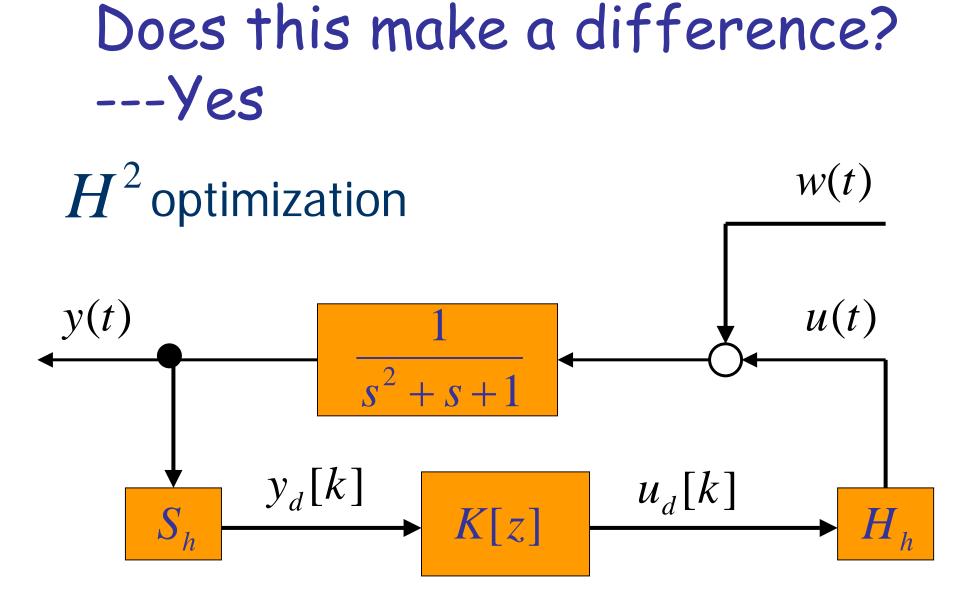


What to do? & solutions

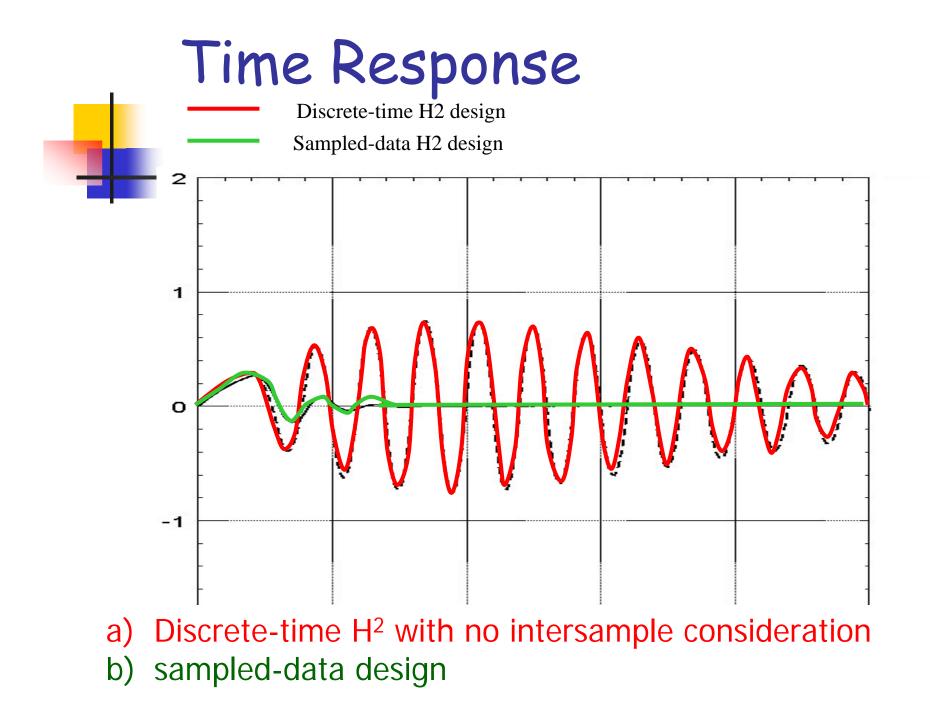
A new technique: *lifting* (1990) that turns SD system to discretetime LTI

digital controller that makes
 cont.-time performance optimal

Lifting of Functions f(t) $f_1(\theta)$ $f_2(\theta)$ $f_0(\theta)$ $f_3(\theta)$



a) Discrete-time H² with no intersample consideration
b) sampled-data design

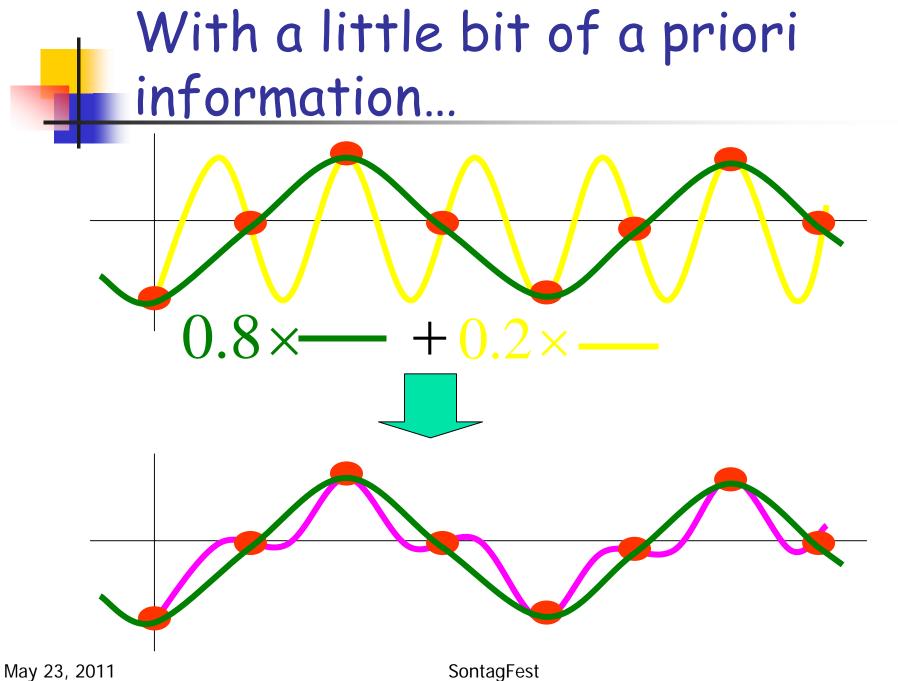


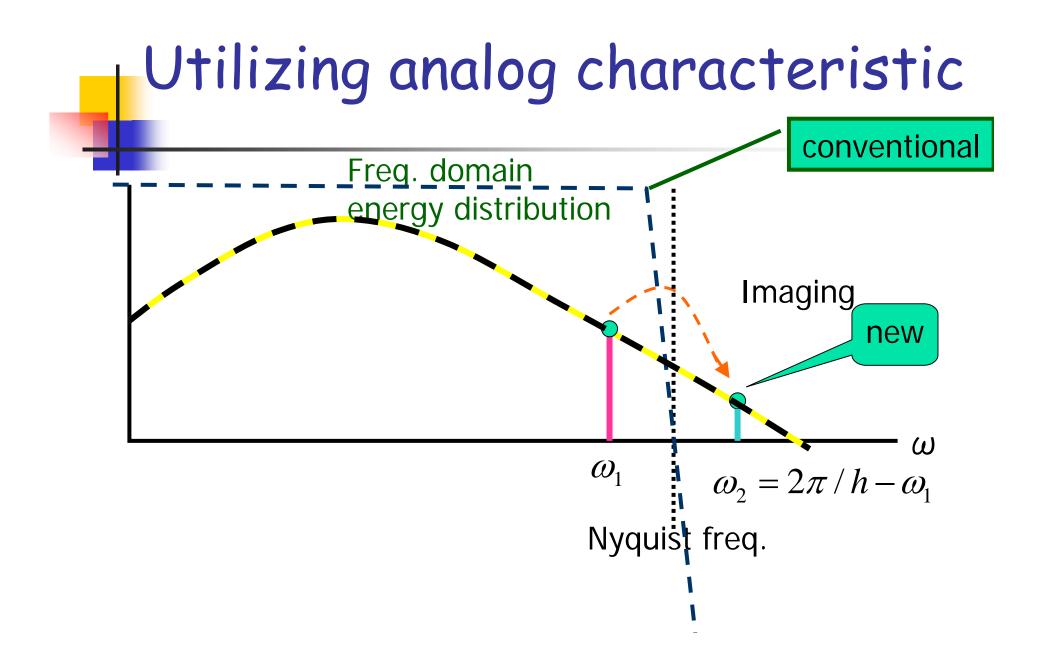


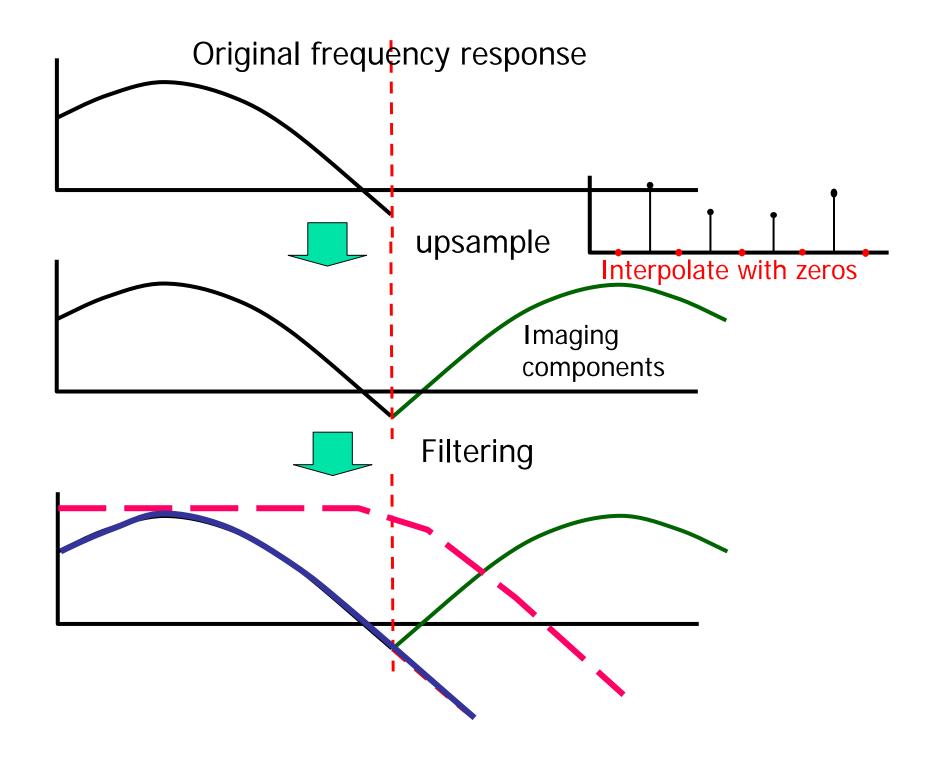
Can this be used for signal processing?

Part III: How can sampled-data theory help?

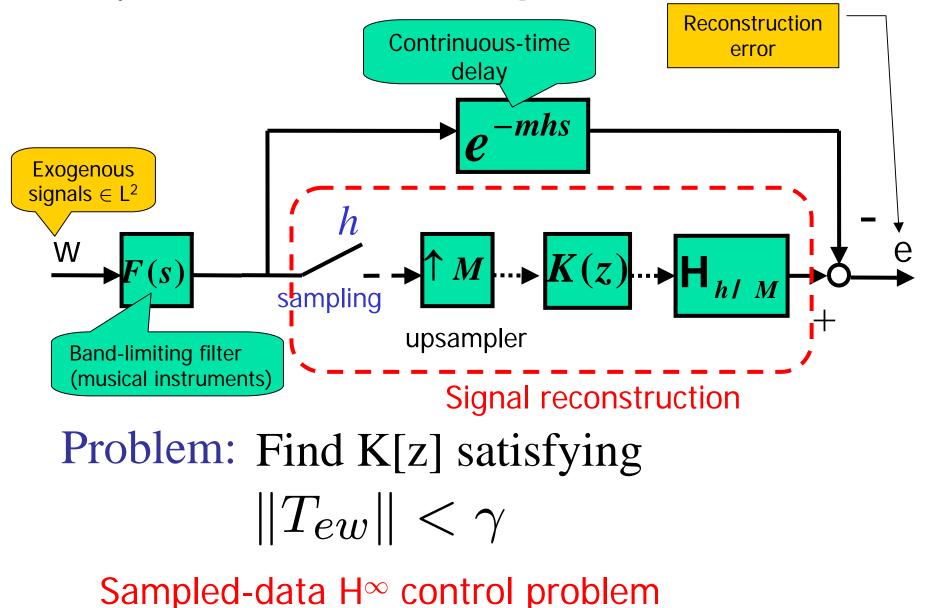


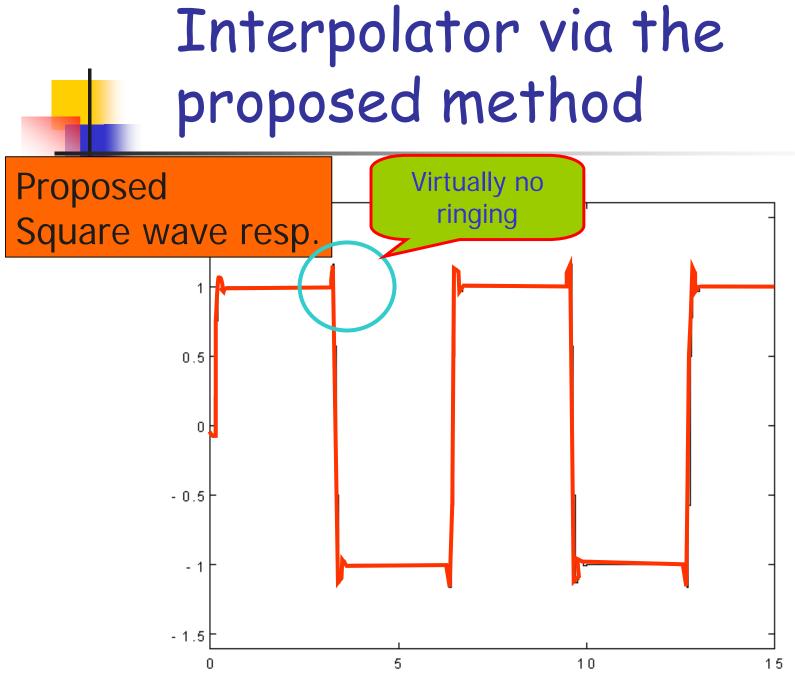






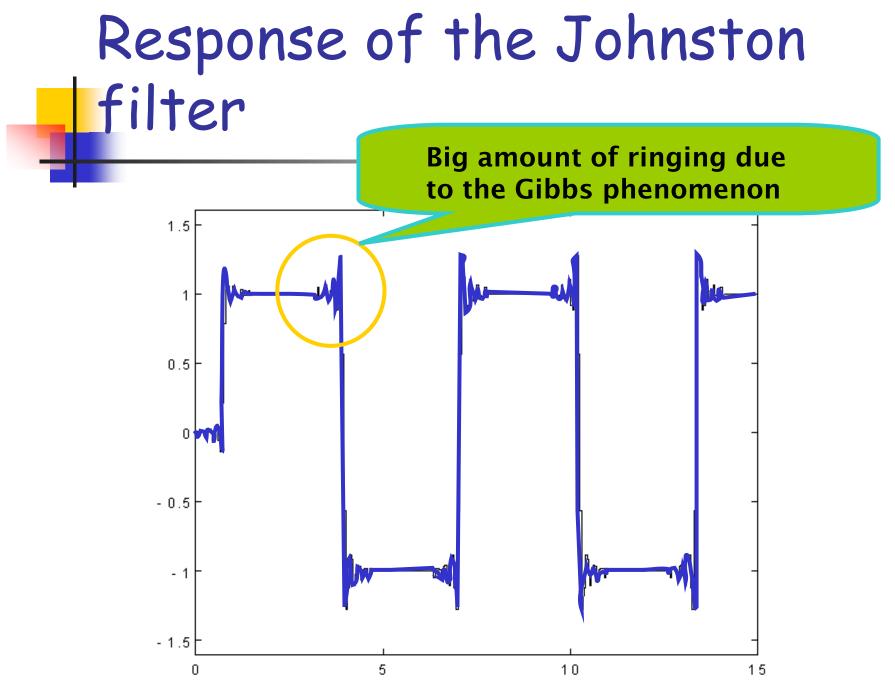
Sampled-data Design Model





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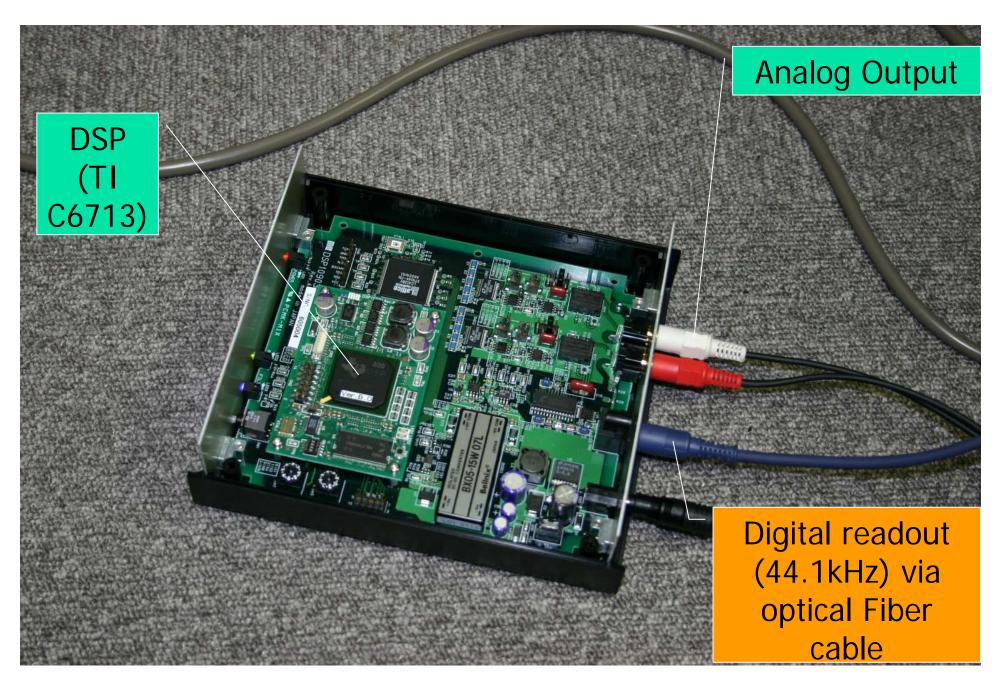
Part IV: Application to Sound Restoration



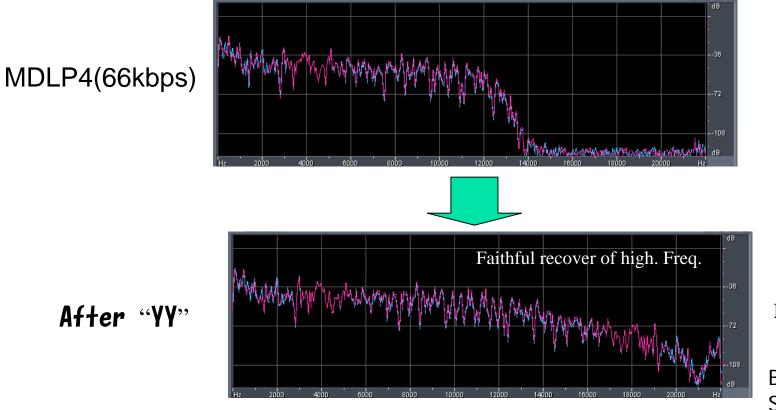








Example in MD(mini disk) players



More natural high freq. response

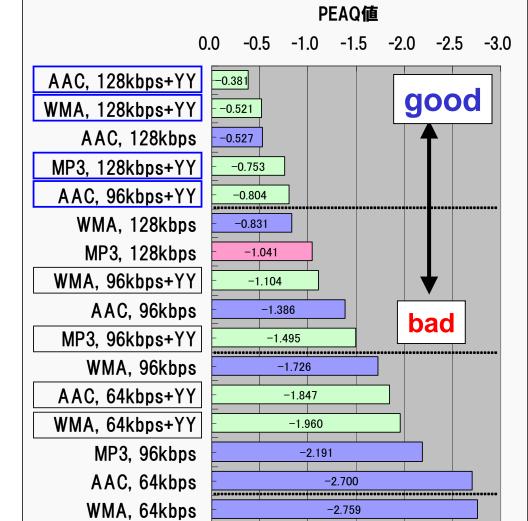
By the courtesy of SANYO Corporation

This "YY filter" is implemented in custom LSI sound chips by SANYO Coop., and being used in MP 3 players, mobile phones, voice recorders. The cumulative sale has reached over 20 million units.

Effect evaluation on compressed audio via PEAQ program

- Tested on 100 compresed music sources via PEAQ (Perceptual Evaluation of Audio Quality)
- PEAQ values:
 - 0...indistinguishable from CD
 - -1...distinguishable but does not bother the listener
 - -2...not disturbing
 - -3...disturbing
 - -4...very disturbing
- Note how YY improves the sound quality
 <u>http://en.wikipedia.org/wiki/PEAQ</u>

By the courtesy of SANYO corporation



Compression formats: MP3, AAC, WMA Bitrates: 64kbps, 96kbps, 128kbps Showing average values

Part V: Application to Images

Same Problems as Sounds

- Block and Mosquito noise
- Lack of sufficient bandwidth
- Mosquito noise Gibbs phenomenon
- Can sampled-data filter help?







Original



↓ 2 downsample
 and hold



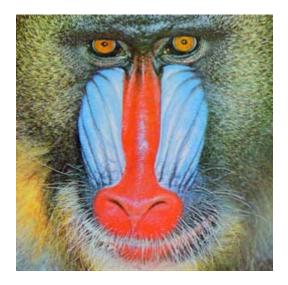
Interpolation Via equiripple filter

4times upsample+ twice downsample via YY

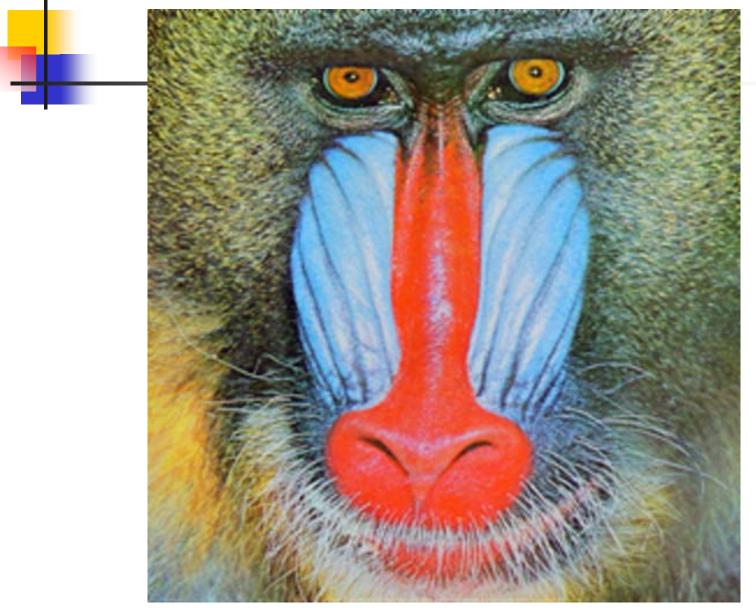
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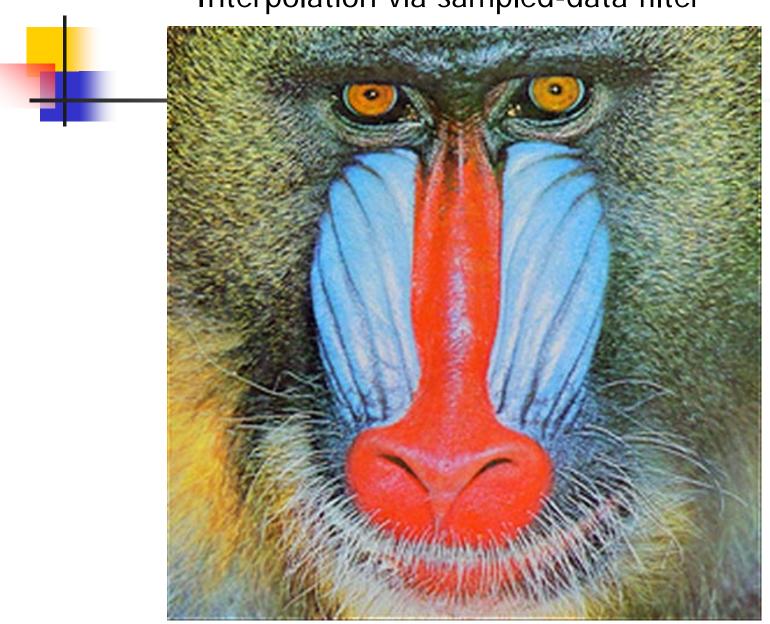
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Another application: How can we zoom "digitally"?



Interpolation via bicubic filter





Interpolation via sampled-data filter

Summarizing

- Analog signal generator model
- Error frequency response to be minimized (doesn't exist in the conventional approach)
- \Leftarrow sampled-data H $^{\infty}$ control

